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**CONSISTENCY OF M-ESTIMATES IN GENERAL  
NONLINEAR REGRESSION MODELS**

Nonlinear regression model with continuous time and weak dependent or long-range dependent stationary noise is considered. Strong consistency sufficient conditions of  $M$ -estimates of regression parameters are obtained.

1. INTRODUCTION

Consider a regression model

$$X(t) = g(y(t), \theta) + \varepsilon(t), \quad t \geq 0, \quad (1)$$

where  $g(y, \tau)$  is a non random function defined on  $Y \times \Theta^c$ ,  $\Theta^c$  is the closure in  $\mathbf{R}^q$  of an open set  $\Theta$ ,  $Y \subset \mathbf{R}^m$  is a compact region of regression experiment design. Borel function  $y(t) : [0, \infty) \rightarrow Y$  is a design of regression experiment,  $\theta = (\theta_1, \dots, \theta_q) \in \Theta^c$  is an unknown parameter. Let  $\varepsilon(t)$ ,  $t \in \mathbf{R}^1$  be a random process satisfying the assumption

**A1.**  $\varepsilon(t)$ ,  $t \in \mathbf{R}^1$  is a real valued mean-square continuous measurable stationary process with zero mean on a complete probability space  $(\Omega, \mathfrak{F}, P)$ .

We do not assume function  $g(y, \theta)$  to be a linear form of coordinates of the vector  $\theta$ .

**Definition 1.**  $M$ -estimate of unknown parameter  $\theta$  obtained by the observations  $X(t)$ ,  $t \in [0, T)$ , of the type (1), is said to be any random vector  $\hat{\theta}_T$  that minimizes in  $\tau \in \Theta^c$  the functional  $M_T(\tau) = \frac{1}{T} \int_0^T \rho(X(t) - g(y(t), \tau)) dt$  with continuous risk function  $\rho : \mathbf{R}^1 \rightarrow \mathbf{R}^1$ .

The consistency property of  $M$ -estimates for nonlinear regression model with independent identically distributed observation errors is considered in [1]. Some facts on consistency of the least squares estimates and least moduli estimates can be found in [2].

Sufficient conditions for strong consistency of  $M$ -estimates of an unknown parameter  $\theta$  of the model (1) with random noise that satisfies weak or long-range dependence conditions are presented in this paper.

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2. ASSUMPTIONS AND THE MAIN RESULTS

Let us impose some restriction on the random process  $\varepsilon(t)$ ,  $t \in \mathbf{R}^1$ .

**A2.**  $\varepsilon(t)$ ,  $t \in \mathbf{R}^1$  is a strictly stationary process, such that for some  $\delta > 0$   $\mu_{2+\delta} = E|\varepsilon(0)|^{2+\delta} < \infty$  and

$$\int_0^\infty (\alpha(r))^{\frac{\delta}{2+\delta}} dr < \infty,$$

where

$$\alpha(r) = \sup_{A \in \sigma(-\infty, s], B \in \sigma[s+r, \infty)} |P(AB) - P(A)P(B)|,$$

$\sigma(a, b]$  is  $\sigma$ -algebra generated by random variables (r.v.)  $\{\varepsilon(t), t \in (a, b]\}$ .

**Definition 2.** If for symmetric r.v.  $\xi$  the probabilities  $P\{|\xi - b| < x\}$ ,  $x \in [0, \infty)$  are nonincreasing functions of the variable  $b \in [0, \infty)$ , then we say that  $\xi$  is a symmetric and unimodal r.v..

**A3.**  $\varepsilon(0)$  is a symmetric and unimodal r.v. with the distribution function (d.f.)  $F(x)$ .

Let  $\mathcal{B}$  be a  $\sigma$ -algebra of Borel subsets of  $Y$ . For any  $A \in \mathcal{B}$

$$\mu_T(A) = T^{-1}m\{t \in [0, T] : y(t) \in A\},$$

where  $m$  is Lebesgue measure on  $[0, \infty)$ .

Let  $\Delta g(y, \tau) = g(y, \theta) - g(y, \tau)$  and  $v_\theta(\varepsilon) = \{\tau \in \mathbf{R}^q : \|\tau - \theta\| < \varepsilon\}$ .

**B1.** The measures  $\mu_T$  are weakly converge, as  $T \rightarrow \infty$ , to some measure  $\mu$ :  $\mu_T \Rightarrow \mu$  and for any  $\varepsilon > 0$   $\mu\{y \in Y : \Delta g(y, \tau) = 0\} < 1$  for each  $\tau \notin v_\theta(\varepsilon)$ .

**Example.** Assume  $\{y_i\}_{i \geq 1} \subset Y$  to be some sequence and  $y(t) = y_i$ ,  $t \in [i - 1; i)$ ,  $i = 1, 2, \dots$ . Introduce the measure

$$\mu_T = \frac{1}{T} \sum_{i=1}^{[T]} \delta_{y_i} + \frac{\{T\}}{T} \delta_{y_{[T]+1}},$$

where  $[T]$  and  $\{T\}$  are integer and fractional parts of  $T$ . Then, if  $\frac{1}{n} \sum_{i=1}^n \delta_{y_i} \Rightarrow \mu$  as  $n \rightarrow \infty$ , then  $\mu_T \Rightarrow \mu$  as  $T \rightarrow \infty$ .

Requirement on the measure  $\mu$  in the condition **B1** can be written as follows: for any  $\varepsilon > 0$   $\mu\{y \in Y : g(y, \tau) \neq g(y, \theta)\} > 0$  for each  $\tau \notin v_\theta(\varepsilon)$ .

Suppose that the measure  $\mu$  is absolutely continuous with respect to Lebesgue measure  $l$  on  $Y$ , furthermore  $l(Y) > 0$  and  $\mu$  has the density  $f(y)$  separated from zero:  $\inf_{y \in Y} f(y) \geq f_* > 0$ . Then

$$\mu\{y \in Y : g(y, \tau) \neq g(y, \theta)\} = \int_{\{y \in Y : g(y, \tau) \neq g(y, \theta)\}} f(y) dy \geq$$

$$\geq f_* l\{y \in Y : g(y, \tau) \neq g(y, \theta)\} > 0,$$

if  $l\{y \in Y : g(y, \tau) \neq g(y, \theta)\} > 0$ . But the last inequality is the property of the regression function to distinguish parameters.

**Definition 3.** Function  $J(\cdot) : \mathbf{R}^1 \rightarrow \mathbf{R}^1$  is called symmetric, if there exists some point  $b_0 \in \mathbf{R}^1$  (which is called the center of symmetry) and some function  $\varphi(\cdot) : [0, \infty) \rightarrow \mathbf{R}^1$  such that  $J(b) = \varphi(|b - b_0|)$ . If  $\varphi$  is a monotonically nondecreasing function and  $\varphi(x) > \varphi(0)$  for  $x > 0$ , then  $J$  is called unimodal and the center of symmetry is called the mode.

Impose some restriction on risk function. Let  $E\rho(\varepsilon(t)) = E\rho(\varepsilon(0)) < \infty$ .

**C1.**  $\rho(x)$  is continuous unimodal, with mode in zero, function such that  $\rho(0) = 0$ .

**C2.** There exists  $c > 0$  such that  $|\rho(x_1) - \rho(x_2)| \leq c|x_1 - x_2|$  for any  $x_1, x_2 \in \mathbf{R}^1$ .

Assume also

**A4.**  $\int_0^\infty [P\{|\varepsilon(0)| < z\} - P\{|\varepsilon(0) - b| < z\}] d\rho(z) > 0, b > 0$ .

Note that from **C1** it follows that  $\rho(x)$  is monotonically nondecreasing function in the region  $x \geq 0$ . It means that Lesbegue-Stilties integral in **A4** exists. Moreover, from **A3** it follows that the difference in square brackets **A4** is nonnegative.

**Theorem 1.** Suppose that assumptions **A1-A4**, **B1**, **C1** and **C2** are fulfilled. Then  $M$ -estimate  $\hat{\theta}_T \rightarrow \theta$  a.s. as  $T \rightarrow \infty$ .

To state the second result of the paper we need to introduce additional condition on  $\varepsilon(t)$ .

**Definition 4.** Stationary process  $\varepsilon(t), t \in \mathbf{R}^1$   $E\varepsilon(t) = 0$  is called a process with long-range dependence if

$$E\varepsilon(0)\varepsilon(t) = B(t) = \frac{L(|t|)}{|t|^\alpha}, \quad 0 < \alpha < 1, \quad (2)$$

where  $L(t) : [0, \infty) \rightarrow [0, \infty)$  is a slowly varying function (at infinity).

**A5.** Gaussian random process  $\varepsilon(t), t \in \mathbf{R}^1$  is a process with long-range dependence,  $B(0) = 1$ .

**Theorem 2.** Suppose that assumptions **A1**, **A4**, **A5**, **B1**, **C1** and **C2** are fulfilled. Then  $M$ -estimate  $\hat{\theta}_T \rightarrow \theta$  a.s. as  $T \rightarrow \infty$ .

### 3. AUXILIARY ASSERTIONS

Set

$$\delta_T(\tau) = Q_T(\tau) - EQ_T(\tau), \quad \Delta_T(\tau) = Q_T(\tau) - Q_T(\theta).$$

**Definition 5.** An unknown parameter  $\theta$  is said to be identifiable, if for any  $\varepsilon > 0$  there exist the numbers  $T_0 = T_0(\varepsilon)$  and  $\delta = \delta(\varepsilon) > 0$  such that  $E\Delta_T(\tau) > \delta$  when  $T > T_0$  and  $\tau \notin v_\theta(\varepsilon)$ .

**Lemma 1.** *Assume that  $\theta$  is identifiable parameter and*

$$\sup_{\tau \in \Theta^c} |\delta_T(\tau)| \xrightarrow{T \rightarrow \infty} 0 \quad \text{a.s.}, \quad (3)$$

then  $\widehat{\theta}_T \rightarrow \theta$  a.s. as  $T \rightarrow \infty$ .

*Proof.* Let us denote by  $\Omega_1$  the event of the probability 1, for which the condition (3) is fulfilled. For elementary events  $\omega \in \Omega_1$  from the definition of the estimate  $\widehat{\theta}_T$  we have

$$\Delta_T(\widehat{\theta}_T) \leq 0. \quad (4)$$

Suppose that for some fixed  $\omega \in \Omega_1$   $\widehat{\theta}_T \not\rightarrow \theta$  as  $T \rightarrow \infty$ . It means that there exists some number  $\varepsilon_0 > 0$  and the sequence of numbers  $T_n \uparrow \infty$  as  $n \rightarrow \infty$  such that for  $n > n(\varepsilon_0)$   $\|\widehat{\theta}_{T_n} - \theta\| \geq \varepsilon_0$ . As for these  $T_n$  (4) also holds, then  $\inf_{\tau \notin v_\theta(\varepsilon_0)} \Delta_{T_n}(\tau) \leq 0$ .

Let  $T_n \geq T_0(\varepsilon_0)$  and for  $n > n(\varepsilon_0)$   $\sup_{\tau \in \Theta^c} |\delta_{T_n}(\tau)| < \frac{\delta_0}{4}$ , where  $\delta_0 = \delta(\varepsilon_0)$ . Then for  $n > n(\varepsilon_0)$

$$\begin{aligned} 0 &\geq \inf_{\tau \notin v_\theta(\varepsilon_0)} \Delta_{T_n}(\tau) = \inf_{\tau \notin v_\theta(\varepsilon_0)} (\delta_{T_n}(\tau) + E\Delta_{T_n}(\tau)) - \delta_{T_n}(\theta) \\ &\geq \inf_{\tau \notin v_\theta(\varepsilon_0)} \delta_{T_n}(\tau) + \inf_{\tau \notin v_\theta(\varepsilon_0)} E\Delta_{T_n}(\tau) - \delta_{T_n}(\theta) \\ &\geq \inf_{\tau \in \Theta^c} \delta_{T_n}(\tau) + \inf_{\tau \notin v_\theta(\varepsilon_0)} E\Delta_{T_n}(\tau) - \delta_{T_n}(\theta) > \frac{\delta_0}{2}. \end{aligned}$$

We obtain contradiction. Hence, for  $\omega \in \Omega_1$   $\widehat{\theta}_T \rightarrow \theta$  as  $T \rightarrow \infty$ .  $\square$

Introduce function  $J(b) = E\rho(\varepsilon(t) - b) = E\rho(\varepsilon(0) - b)$ ,  $b \in \mathbf{R}^1$ .

The next lemma states sufficient conditions of identifiability of parameter  $\theta$ .

**Lemma 2.** *An unknown parameter  $\theta$  is identifiable if*

(i) *for any  $\varepsilon > 0$  there exist  $T_0 = T_0(\varepsilon)$  and  $x = x(\varepsilon) > 0$  such that for any  $T > T_0$  and any  $\tau \notin v_\theta(\varepsilon)$   $\mu_T \{y \in Y : |\Delta g(y, \tau)| > x\} > x$ ;*

(ii)  *$J(b)$  is unimodal;*

(iii)  *$J(b) > J(0)$  for any  $b \neq 0$ .*

*Proof.* It is easily seen that under the conditions (ii) and (iii) the mode is in  $b = 0$ . Furthermore,

$$E\Delta_T(\tau) = \frac{1}{T} \int_0^T [J(\Delta g(y(t), \tau)) - J(0)] dt. \quad (5)$$

Fix some  $\varepsilon > 0$  and consider numbers  $T_0$  and  $x$  taken from the condition (i) of the Lemma. From the condition (ii) it follows that the right hand side of

the relation (5) permits the lower bound

$$\begin{aligned} \frac{1}{T} \int_0^T [J(\Delta g(y(t), \tau)) - J(0)] dt &\geq (J(x) - J(0)) \frac{1}{T} \int_0^T \chi_{(x, \infty)} (|\Delta g(y(t), \tau)|) dt \\ &= (J(x) - J(0)) \mu_T \{y \in Y : |\Delta g(y, \tau)| > x\}, \end{aligned}$$

where  $\chi_A(x)$  is the indicator of the set  $A$ .

From (i) and (ii) it follows that in the definition of the identifiability of parameter one can set  $\delta = x(J(x) - J(0))$ .  $\square$

Further we formulate some sufficient conditions on the validity of Lemmas 1 and 2.

**Lemma 3.** *If the assumption **B1** holds, then the condition (i) of the Lemma 2 fulfils.*

*Proof.* Let  $\varepsilon > 0$  be an arbitrary number. It is necessary to show that there exists some numbers  $T_0$  and  $x > 0$  such that

$$\mu_T \{y \in Y : |\Delta g(y, \tau)| > x\} > x, \quad T > T_0, \quad \tau \notin v_\theta(\varepsilon). \quad (6)$$

Assume that (6) does not hold. Then there exist some sequences  $T_n \uparrow \infty$  as  $n \rightarrow \infty$  and  $\tau_n \in \Theta^c \setminus v_\theta(\varepsilon)$  such that

$$\mu_{T_n} \{y \in Y : |\Delta g(y, \tau_n)| > n^{-1}\} \leq n^{-1}, \quad n \geq 1. \quad (7)$$

As the set  $\Theta^c \setminus v_\theta(\varepsilon)$  is compact, there exists some point  $\tau^* \in \Theta^c \setminus v_\theta(\varepsilon)$  and the sequence  $n_k$ ,  $k \geq 1$  such that  $\tau_{n_k} \rightarrow \tau^*$  as  $k \rightarrow \infty$ .

Let  $\delta > 0$  be an arbitrary fixed number. Then there exists some number  $k_\delta$  such that for  $k > k_\delta$ , uniformly in  $y \in Y$ ,

$$|\Delta g(y, \tau_{n_k}) - \Delta g(y, \tau^*)| \leq \frac{\delta}{2}. \quad (8)$$

Thanks to (8), for  $k > k_\delta$

$$\begin{aligned} \{|\Delta g(y, \tau^*)| > \delta\} &\subset \{|\Delta g(y, \tau^*) - \Delta g(y, \tau_{n_k})| + |\Delta g(y, \tau_{n_k})| > \delta\} \\ &\subset \left\{|\Delta g(y, \tau_{n_k})| > \frac{\delta}{2}\right\}. \end{aligned} \quad (9)$$

Taking into account the inequality (7) for  $n_k > \frac{2}{\delta}$  one has

$$\mu_{T_{n_k}} \left\{y \in Y : |\Delta g(y, \tau_{n_k})| > \frac{\delta}{2}\right\} \leq \frac{1}{n_k}. \quad (10)$$

Then, from (9) and (10) it follows that

$$\mu_{T_{n_k}} \{y \in Y : |\Delta g(y, \tau^*)| > \delta\} \leq n_k^{-1}, \quad (11)$$

which is true for any  $k > k'_\delta = \max(k_\delta, \min\{k : n_k > \frac{2}{\delta}\})$ .

Denote by  $Y_\delta = \{y \in Y : |\Delta g(y, \tau^*)| \leq \delta\}$ . From (11) it follows that  $\mu_{T_{n_k}}(Y_\delta) > 1 - n_k^{-1}$  for all  $k > k'_\delta$ .

As  $Y_\delta$  is a closed set, then thanks to weak convergence of  $\mu_T$  to the measure  $\mu$ , we obtain (see, for example, [3], p. 21)

$$\overline{\lim}_{k \rightarrow \infty} \mu_{T_{n_k}}(Y_\delta) \leq \mu(Y_\delta), \quad \delta > 0.$$

For  $\delta \downarrow 0$ , from the continuity of the measure  $\mu$  it follows that

$$\mu\{y \in Y : \Delta g(y, \tau) = 0\} = 1. \tag{12}$$

But the relation (12) contradicts to the condition **B1**.  $\square$

**Lemma 4.** *If the assumptions **A3**, **A4** and **C1** hold, then the conditions (ii) and (iii) of the Lemma 2 are fulfilled.*

*Proof.* Without loss of generality, assume that  $\rho(x)$ ,  $x \geq 0$  is strictly monotonically increasing function. From the formula for the mean of the nonnegative r.v. (see, for example, [4], p. 190) one has

$$J(b) - J(0) = \int_0^\infty (P\{\rho(\varepsilon(0)) < x\} - P\{\rho(\varepsilon(0) - b) < x\}) dx =$$

$$\int_0^\infty (P\{-\rho^{-1}(x) < \varepsilon(0) < \rho^{-1}(x)\} - P\{-\rho^{-1}(x) < \varepsilon(0) - b < \rho^{-1}(x)\}) dx,$$

where  $\rho^{-1}(x)$  is the inverse of the function  $\rho(x)$ ,  $x \geq 0$ .

By the change of variable  $x = \rho(z)$ ,  $z \geq 0$  in the last integral,

$$J(b) - J(0) = \int_0^\infty (P\{|\varepsilon(0)| < z\} - P\{|\varepsilon(0) - b| < z\}) d\rho(z) =$$

$$= \int_0^\infty (F(z) - F(z - b) - F(z + b) + F(z)) d\rho(z), \tag{13}$$

where  $F(x)$  is the d.f. of the r.v.  $\varepsilon(0)$ .

The integral in the first equality of the relations (13) coincides with the expression of **A4**, and the condition (iii) of Lemma 2 is fulfilled.

From the symmetry of  $\rho$  and r.v.  $\varepsilon(0)$  it follows the symmetry of  $J(b)$ .

Denote by  $\Delta_b^2 F(z) = (F(z) - F(z - b)) - (F(z + b) - F(z))$ ,  $b, z \geq 0$ . Then **A4** can be rewritten in the form

$$\int_0^\infty \Delta_b^2 F(z) d\rho(z) > 0, \quad b > 0.$$

From (13) it follows that

$$\Delta_b^2 F(z) = P\{|\varepsilon(0)| < z\} - P\{|\varepsilon(0) - b| < z\}.$$

Consider for  $b_2 > b_1$  the difference

$$J(b_2) - J(b_1) = \int_0^\infty (\Delta_{b_2}^2 F(z) - \Delta_{b_1}^2 F(z)) d\rho(z).$$

It is easily seen that

$$\Delta_{b_2}^2 F(z) - \Delta_{b_1}^2 F(z) = P\{|\varepsilon(0) - b_1| < z\} - P\{|\varepsilon(0) - b_2| < z\} \geq 0$$

from the unimodality of the r.v.  $\varepsilon(0)$ . It means that  $J(b_2) - J(b_1) \geq 0$ , and the condition (ii) of Lemma 2 is a corollary of **A3** and **C1**.  $\square$

Assume that the d.f.  $F(x)$  is continuously differentiable and the density of the distribution  $p(x)$  is an even strictly decreasing for  $x \geq 0$  function. Suppose that a continuous even function  $\rho(x)$  is such that  $\rho(0) = 0$  and strictly monotonically increasing for  $x \geq 0$ . Then one can use Lemma 10.2 of the book [3], p. 217-218, and for any  $b \neq 0$

$$J(b) - J(0) = E\rho(\varepsilon(0) - b) - E\rho(\varepsilon(0)) > 0,$$

and the integral in **A4** is strictly positive.

Consider next sufficient conditions of the uniform convergence in (3) of Lemma 1.

**Lemma 5.** *Suppose the condition **C2** fulfils and*

$$\delta_T(\tau) \xrightarrow{T \rightarrow \infty} 0 \quad \text{a.s., } \tau \in \Theta^c, \quad (14)$$

then (3) holds.

*Proof.* From **C2** it follows that for  $\tau_1, \tau_2 \in \Theta^c$

$$|Q_T(\tau_1) - Q_T(\tau_2)| \leq \frac{c}{T} \int_0^T |g(y(t), \tau_1) - g(y(t), \tau_2)| dt.$$

Similarly, from **C2** for  $\tau_1, \tau_2 \in \Theta^c$  one has

$$|\delta_T(\tau_1) - \delta_T(\tau_2)| \leq \frac{2c}{T} \int_0^T |g(y(t), \tau_1) - g(y(t), \tau_2)| dt.$$

Hence, the family of functions  $\{\delta_T(\tau) : \omega \in \Omega, T > 0\}$  is an equicontinuous on the set  $\Theta^c$ . So for any  $\delta > 0$  there exists a finite number of points  $\tau_1, \dots, \tau_k \in \Theta^c$  such that

$$\sup_{\tau \in \Theta^c} |\delta_T(\tau)| \leq \max_{1 \leq j \leq k} |\delta_T(\tau_j)| + \delta, \quad \omega \in \Omega, T > 0.$$

From (14) it follows that  $\max_{1 \leq j \leq k} |\delta_T(\tau_j)| \rightarrow 0$  a.s. as  $T \rightarrow \infty$ , and, hence,  $\sup_{\tau \in \Theta^c} |\delta_T(\tau)| \rightarrow 0$  a.s. as  $T \rightarrow \infty$ .  $\square$

## 4. PROOF OF THEOREM 1

We shall prove that (14) holds under the assumptions of Theorem 1. Using the notation

$$\xi(t) = \rho(\varepsilon(t) - \Delta g(y(t), \tau)) - E\rho(\varepsilon(t) - \Delta g(y(t), \tau)), \quad \tau \in \Theta^c$$

one has

$$\begin{aligned} \delta_T(\tau) &= \frac{1}{T} \int_0^T \xi(t) dt, \quad E\delta_T^2(\tau) = \frac{1}{T^2} \int_0^T \int_0^T E\xi(t)\xi(s) dt ds \leq \\ &\leq \frac{10}{T^2} \int_0^T \int_0^T [E\rho^{2+\delta}(\varepsilon(t) - \Delta g(y(t), \tau))]^{\frac{1}{2+\delta}} \times \\ &\quad \times [E\rho^{2+\delta}(\varepsilon(s) - \Delta g(y(s), \tau))]^{\frac{1}{2+\delta}} \alpha^{\frac{\delta}{2+\delta}}(|t-s|) dt ds. \end{aligned} \quad (15)$$

To obtain (15) the Davidov inequality has been used with  $p = q = 2 + \delta$ ,  $r = 1 + \frac{2}{\delta}$  (see [5], and also Lemma 1.6.2 of the book [6]).

As  $\rho(0) = 0$ , then from the condition **C2** one obtains

$$E\rho^{2+\delta}(\varepsilon(t) - \Delta g(y(t), \tau)) \leq c^{2+\delta} E|\varepsilon(0) - \Delta g(y(t), \tau)|^{2+\delta}.$$

By obvious inequalities

$$\begin{aligned} |a+b|^\kappa &\leq 2^{\kappa-1}(|a|^\kappa + |b|^\kappa), \quad |a+b|^{\frac{1}{\kappa}} \leq |a|^{\frac{1}{\kappa}} + |b|^{\frac{1}{\kappa}}, \quad \kappa = 2 + \delta, \quad (16) \\ [E\rho^{2+\delta}(\varepsilon(t) - \Delta g(y(t), \tau))]^{\frac{1}{2+\delta}} &\leq 2^{\frac{1+\delta}{2+\delta}} c \left( \mu_{2+\delta}^{\frac{1}{2+\delta}} + |\Delta g(y(t), \tau)| \right), \end{aligned}$$

i.e.

$$\begin{aligned} E\delta_T^2(\tau) &\leq 2^{\frac{\delta}{2+\delta}} c^2 \frac{20}{T^2} \int_0^T \int_0^T \alpha^{\frac{\delta}{2+\delta}}(|t-s|) \left[ \mu_{2+\delta}^{\frac{1}{2+\delta}} + |\Delta g(y(t), \tau)| \right] \times \\ &\quad \times \left[ \mu_{2+\delta}^{\frac{1}{2+\delta}} + |\Delta g(y(s), \tau)| \right] dt ds \leq \\ &\leq 2^{\frac{\delta}{2+\delta}} c^2 \frac{20}{T^2} \int_0^T \int_0^T \alpha^{\frac{\delta}{2+\delta}}(|t-s|) \left[ \mu_{2+\delta}^{\frac{1}{2+\delta}} + |\Delta g(y(t), \tau)| \right]^2 dt ds. \end{aligned}$$

Using the first inequality of (16) with  $\kappa = 2$ ,

$$E\delta_T^2(\tau) \leq 2^{\frac{\delta}{2+\delta}} c^2 \frac{40}{T^2} \int_0^T \int_0^T \alpha^{\frac{\delta}{2+\delta}}(|t-s|) \left[ \mu_{2+\delta}^{\frac{2}{2+\delta}} + |\Delta g(y(t), \tau)|^2 \right] dt ds.$$



It remains to estimate two integrals, namely:

$$I_1 = \frac{1}{T^2} \int_0^T \int_0^T \alpha^{\frac{\delta}{2+\delta}}(|t-s|) dt ds \leq \frac{1}{T^2} \int_0^T ds \int_{-T}^T \alpha^{\frac{\delta}{2+\delta}}(|t|) dt = O(T^{-1})$$

as  $T \rightarrow \infty$ , under assumption **A2**. On the other hand,

$$\begin{aligned} I_2 &= \frac{1}{T^2} \int_0^T \int_0^T \alpha^{\frac{\delta}{2+\delta}}(|t-s|) |\Delta g(y(t), \tau)|^2 dt ds \\ &\leq \left( 2 \int_0^\infty \alpha^{\frac{\delta}{2+\delta}}(s) ds \right) \frac{1}{T^2} \int_0^T |\Delta g(y(t), \tau)|^2 dt. \end{aligned} \quad (17)$$

As  $g(y, \tau)$  is continuous function on the compact  $Y \times \Theta^c$ , the right hand side of the inequality (17) is of the order  $O(T^{-1})$  as  $T \rightarrow \infty$ .

Thus,  $E\delta_T^2(\tau) = O(T^{-1})$  as  $T \rightarrow \infty$ , and  $\delta_T(\tau) \rightarrow 0$  in probability as  $T \rightarrow \infty$ .

Note that for the sequence  $T_n = n^2$ ,  $n \geq 1$   $\sum_{n=1}^\infty E\delta_{T_n}^2(\tau) < \infty$ , i.e.  $\delta_{T_n}(\tau) \xrightarrow{n \rightarrow \infty} 0$  a.s.

If  $T \in [T_n, T_{n+1}]$ , then

$$|\delta_T(\tau)| \leq \sup_{T_n \leq T \leq T_{n+1}} |\delta_T(\tau) - \delta_{T_n}(\tau)| + |\delta_{T_n}(\tau)|,$$

and the Theorem will be proved, if  $\sup_{T_n \leq T \leq T_{n+1}} |\delta_T(\tau) - \delta_{T_n}(\tau)| \xrightarrow{n \rightarrow \infty} 0$  a.s.

Obviously

$$\begin{aligned} \delta_T(\tau) - \delta_{T_n}(\tau) &= \frac{1}{T} \int_0^T \xi(t) dt - \frac{1}{T_n} \int_0^{T_n} \xi(t) dt = \\ &= \left( \frac{1}{T} - \frac{1}{T_n} \right) \int_0^{T_n} \xi(t) dt + \frac{1}{T} \int_{T_n}^T \xi(t) dt = I_3 + I_4. \end{aligned}$$

Furthermore, for  $T \in [T_n, T_{n+1}]$

$$|I_3| \leq \frac{T_{n+1} - T_n}{T_n} |\delta_{T_n}(\tau)| \xrightarrow{n \rightarrow \infty} 0 \text{ a.s.};$$

$$|I_4| \leq \frac{1}{T_n} \int_{T_n}^{T_{n+1}} |\xi(t)| dt \leq \frac{1}{T_n} \int_{T_n}^{T_{n+1}} \rho(\varepsilon(t) - \Delta g(y(t), \tau)) dt +$$

$$+\frac{1}{T_n} \int_{T_n}^{T_{n+1}} E\rho(\varepsilon(t) - \Delta g(y(t), \tau)) dt = I_5 + I_6.$$

As under the Lipschitz condition **C2**

$$\rho(\varepsilon(t) - \Delta g(y(t), \tau)) \leq c(|\varepsilon(t)| + |\Delta g(y(t), \tau)|),$$

then

$$I_5 \leq \frac{c}{T_n} \int_{T_n}^{T_{n+1}} |\varepsilon(t)| dt + \frac{c}{T_n} \int_{T_n}^{T_{n+1}} |\Delta g(y(t), \tau)| dt = I_7 + I_8,$$

$$I_8 = c \left( \frac{T_{n+1}}{T_n} \cdot \frac{1}{T_{n+1}} \int_0^{T_{n+1}} |\Delta g(y(t), \tau)| dt - \frac{1}{T_n} \int_0^{T_n} |\Delta g(y(t), \tau)| dt \right).$$

From the assumption **B1** of the Theorem it follows

$$\frac{1}{T_n} \int_0^{T_n} |\Delta g(y(t), \tau)| dt = \int_Y |\Delta g(y, \tau)| \mu_{T_n}(dy) \xrightarrow{n \rightarrow \infty} \int_Y |\Delta g(y, \tau)| \mu(dy),$$

then  $I_8 \rightarrow 0$  as  $n \rightarrow \infty$ .

On the other hand,

$$I_7 = c \left( \frac{1}{T_n} \int_{T_n}^{T_{n+1}} (|\varepsilon(t)| - E|\varepsilon(t)|) dt + E|\varepsilon(0)| \frac{T_{n+1} - T_n}{T_n} \right) \xrightarrow{n \rightarrow \infty} 0 \text{ a.s.}$$

by Davidov inequality.

Similarly, it can be shown that  $I_6 \rightarrow 0$  as  $n \rightarrow \infty$ .

Consequently, (14) is fulfilled. The validity of Theorem 1 follows now from the Lemmas 1-5 proved above.  $\square$

## 5. PROOF OF THEOREM 2

Similarly to proof of Theorem 1 we need to proof that (14) holds. Then the result of Theorem 2 will follow from the Lemmas 1-5.

Consider a random process

$$G(\varepsilon(t), t) = \rho(\varepsilon(t) - \Delta g(y(t), \tau)). \tag{18}$$

From **C2** and **A5**

$$EG^2(\varepsilon(t), t) \leq c^2 E |\varepsilon(t) - \Delta g(y(t), \tau)|^2 = c^2 (1 + |\Delta g(y(t), \tau)|^2) \leq C < \infty \tag{19}$$

uniformly in  $t \geq 0$  and  $\tau \in \Theta^c$ . Therefore in Gilbert space  $L_2(\mathbf{R}^1, \varphi(u)du)$ , where  $\varphi(x) = \frac{1}{\sqrt{2\pi}}e^{-\frac{x^2}{2}}$  is a standard Gaussian density, there exists an expansion (see, for example, [6])

$$G(u, t) = \sum_{m=0}^{\infty} \frac{C_m(t)}{m!} H_m(u), \quad C_m(t) = \int_{\mathbf{R}^1} G(u, t) H_m(u) \varphi(u) du, \quad m \geq 0$$

by Chebyshev-Hermite polynomials

$$H_m(u) = (-1)^m e^{\frac{u^2}{2}} \frac{d^m}{du^m} e^{-\frac{u^2}{2}}, \quad m \geq 0. \quad (20)$$

Note that  $C_0(t) = E\rho(\varepsilon(0) - \Delta g(y(t), \tau)) = J(\Delta g(y(t), \tau))$ . Thanks to relations

$$E H_m(\varepsilon(t)) H_k(\varepsilon(s)) = \delta_m^k m! B^m(t-s), \quad (21)$$

where  $\delta_m^k$  is Kroneker delta we have

$$E\xi(t)\xi(s) = \text{cov}(G(\varepsilon(t), t), G(\varepsilon(s), s)) = \sum_{m=1}^{\infty} \frac{C_m(t)C_m(s)}{m!} B^m(t-s).$$

Hence, taking into account that  $B(0) = 1$ , we obtain

$$\begin{aligned} E\delta_T^2(\tau) &= \sum_{m=1}^{\infty} \frac{1}{m!} \frac{1}{T^2} \int_0^T \int_0^T C_m(t) C_m(s) B^m(t-s) dt ds \\ &\leq \sum_{m=1}^{\infty} \frac{1}{m!} \frac{1}{T^2} \int_0^T \int_0^T C_m^2(t) B^m(t-s) dt ds \\ &\leq \frac{1}{T^2} \int_0^T \int_0^T \left( \sum_{m=1}^{\infty} \frac{C_m^2(t)}{m!} \right) B(t-s) dt ds. \end{aligned}$$

Note that, thanks to (19),

$$\sum_{m=1}^{\infty} \frac{C_m^2(t)}{m!} = EG^2(\varepsilon(0), t) - (EG(\varepsilon(0), t))^2 = DG(\varepsilon(0), t) \leq C < \infty,$$

and

$$E\delta_T^2(\tau) \leq C \frac{1}{T^2} \int_0^T \int_0^T B(t-s) dt ds.$$

On the other hand, as  $T \rightarrow \infty$ ,

$$\begin{aligned} \frac{1}{T^2} \int_0^T \int_0^T B(t-s) dt ds &= \int_0^1 \int_0^1 B(T(t-s)) dt ds = \frac{1}{T^\alpha} \int_0^1 \int_0^1 \frac{L(T|t-s|)}{|t-s|^\alpha} dt ds \\ &\sim \left( \int_0^1 \int_0^1 \frac{dt ds}{|t-s|^\alpha} \right) \frac{L(T)}{T^\alpha} = \frac{2}{(1-\alpha)(2-\alpha)} \frac{L(T)}{T^\alpha} \end{aligned}$$

by the properties of the slowly varying function (see, for example [7],[8]).

For the sequence  $T_n = n^{\frac{1}{\alpha} + \nu}$ , where  $\nu > 0$  is some number,  $\sum_{n=1}^{\infty} \frac{L(T_n)}{T_n^\alpha} < \infty$ , and so  $\delta_{T_n}(\tau) \rightarrow 0$  a.s., as  $n \rightarrow \infty$ .

Taking into account the proof of Theorem 1, it remains to show that

$$\frac{1}{T_n} \int_0^{T_n} (|\varepsilon(t)| - E|\varepsilon(t)|) dt \xrightarrow[n \rightarrow \infty]{} 0 \text{ a.s.} \tag{22}$$

But the proof of (22) is similar to the previous reasoning for  $G(\varepsilon(t), t)$ .  $\square$

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