ON λ -STABILITY OF ONE ESSENTIALLY NONLINEAR NONAUTONOMOUS SECOND ORDER EQUATION

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There are obtained sufficient conditions for λ -stability of the trivial solution of a some essentially nonlinear differential second order equation.

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1. Setting of the Problem

The subject of investigation in the theory of wave propagation [1] is the behavior of solutions of the second order differential equation (d.e.) with respect to degrees of the coefficient at the first degree of the unknown function in the theory of a diffusion of waves. Therefore in what follows we investigate asymptotic local and global λ -stability of the d.e. of the type

$$y'' + \lambda(t)y = F(t, y, y'), \tag{1}$$

where $t \in \Delta$, $\Delta \equiv [t_0, \omega[$ or $\Delta \equiv]\omega, t_0]$, $|\omega| \leq +\infty$, $\lambda : \Delta \mapsto \mathbf{R}_+$, $F : \Delta \times \mathbf{R}^2 \mapsto \mathbf{R}$, $\mathbf{R} \equiv]-\infty, +\infty[$, $\mathbf{R} \equiv]-\infty, +\infty[$, $\mathbf{R} \equiv]-\infty, 0[$, $\mathbf{R}_+ \equiv]0, +\infty[$, $\mathbf{R}^2 \equiv \mathbf{R} \times \mathbf{R}$, $\lambda \in \mathbf{C}^1_\Delta$, $F \equiv \sum_{s+k=2}^m f_{s,k} y^s (y')^k + F^*, f_{sk} \in \mathbf{C}^1_\Delta$, $s+k=\overline{2,m}$, $m \in \{3,4,\dots\}$, $|F^*| \leq L (|y|+|y'|)^{m+\alpha}$, $L \in \mathbf{C}_\Delta$, $L : \Delta \mapsto$

 $\mathbf{R}_+, \alpha \in \mathbf{R}_+$. The results given below are applied to the d.e. (1) with slowly variable coefficients (their derivates are smalls with respect to the coefficients themselves as $t \uparrow \omega$). Let us denote

$$S(t, \lambda, a, b) \equiv \frac{|y(t; t_0, y_0, y_0')|}{\lambda^a} + \frac{|y'(t; t_0, y_0, y_0')|}{\lambda^b},$$

where $y = y(t; y_0, y'_0)$ is a solution of the d.e. (1), $a, b \in \mathbf{R}$;

$$B_{sk}(t;a,b) \equiv 0.5 \sum_{p=0}^{k+p-q} \sum_{q=0}^{s-p+q} (-1)^p i^{k+p-q} \lambda^{(a+b)(s+k-1)-\frac{1}{2}(k+p-q)} C_{k+p-q}^p C_{s-p+q}^q f_{k+p-q,s-p+q},$$

$$i^2 = -1;$$

$$\Lambda \equiv \max\{f_s : \mathbf{\Delta} \mapsto \mathbf{R}; \ s = \overline{1, n}\},\$$

if
$$\Lambda: \Delta \mapsto \mathbf{R}_+, \Lambda^{-1}f_s = c_s + o_s(1), t \uparrow \omega, c_s \in \mathbf{R}, s = \overline{1, n}, |c_1| + \ldots + |c_n| > 0;$$

$$L^*(t; a, b) \equiv 2^{m+\alpha-1} \lambda^{(a+b-\frac{1}{4})(m+\alpha)} (\lambda^{-\frac{1}{4}} + \lambda^{\frac{1}{4}})^{m+\alpha} L;$$

$$G(t, a, b, x) \equiv \sum_{\substack{s+k=2\\s\neq k+1}}^{m} \Lambda^{-1}(t; a, b) |B_{s,k}(t; a, b)| \phi^{s+k-1}(t; a, b) x^{s+k}$$

$$+ \sum_{s=1}^{m_0} \left| \Lambda^{-1}(t; a, b) \operatorname{Re} B_{s+1,s}(t; a, b) \phi^{2s}(t; a, b) - B_{2s+1}(a, b) \right| x^{2s+1}$$

$$+ \phi^{m+\alpha-1}(t; a, b) \Lambda^{-1}(t; a, b) L^*(t; a, b) x^{m+\alpha}; \ m_0 = \frac{m}{2} - \frac{3 + (-1)^m}{4}.$$

Definition 1. The d.e. (1) has the property St_{λ} as $t \uparrow \omega$ if there are constants $a, b \in \mathbf{R}$ such that for any arbitrarily small $\varepsilon \in \mathbf{R}_+$ there are $T_{\varepsilon} \in \Delta$, $\delta_{\varepsilon} \in]0, \varepsilon[$, such that any solution $y = y(t; T_{\varepsilon}, y_0, y_0')$ with an initial condition $S(T_{\varepsilon}, \lambda, a, b) \leq \delta_{\varepsilon}$ satisfies the inequality $S(t, \lambda, a, b) < \varepsilon$ for all $t \in [T_{\varepsilon}, \omega[$ (the local λ -stability).

Definition 2. The d.e. (1) has the property $AsSt_{\lambda}$ as $t \uparrow \omega$ if Definition 1 takes place and $S(T_{\varepsilon}, \lambda, a, b) = o(1), t \uparrow \omega$ (the local asymptotic λ -stability).

Definition 3. The d.e. (1) has the property $G_{\Delta}St_{\lambda}$ as $t \uparrow \omega$ if there are constants $a, b \in \mathbb{R}$ such that for any arbitrarily small $\varepsilon \in \mathbb{R}_+$ there is $\delta_{\varepsilon} \in]0, \varepsilon[$ such that any solution $y = y(t; t_0, y_0, y_0')$ of the d.e. with an initial condition $S(t_0, \lambda, a, b) \leq \delta_{\varepsilon}$ satisfies the inequality $S(t, \lambda, a, b) < \varepsilon$ for all $t \in \Delta$ (the global λ -stability).

Definition 4. The d.e. (1) has the property $G_{\Delta}AsSt_{\lambda}$ as $t \uparrow \omega$ if Definition 3 takes place and $S(t, \lambda, a, b) = o(1)$, $t \uparrow \omega$ (the global asymptotic λ -stability).

Definition 5. The d.e. (1) has the property $UnSt_{\lambda}$ as $t \uparrow \omega$, if the Definition 1 doesn't take place.

2. Auxiliary Results

Let us give tranformations that help to obtain an estimate of the value $S(t, \lambda, a, b)$.

Lemma 1. The transformation

$$y = -i\lambda^{a+b-0.5}(x-\overline{x}), \quad y' = \lambda^{a+b}(x+\overline{x}), \tag{2}$$

reduces the d.e. (1) to the d.e. of the type

$$x' = \Phi(t, x), \tag{3}$$

where

$$\Phi(t,x) \equiv \left[i\lambda^{0,5} - (a+b-0,25)\lambda'\lambda^{-1} \right] x - 0,25\lambda'\lambda^{-1}\overline{x} + \sum_{s+k=2}^{m} B_{s,k}(t;a,b)x^{s}\overline{x}^{k} + \Phi^{*}(t,x),$$

$$\Phi^*(t,x) \equiv \frac{1}{2} \lambda^{-(a+b)} F^*[t, -i\lambda^{a+b-0.5}(x-\overline{x}), \lambda^{a+b}(x+\overline{x})], \ |\Phi^*| \le L^*(t;a,b) |x|^{m+\alpha}.$$

Proof is obvious.

Lemma 2. The substitution

$$x = \rho \exp(i\theta), \ \rho = |x|, \ \theta \in \mathbf{R},$$
 (4)

reduces the d.e. (3) to the differential system (d.s.) of the type

$$\rho' = -(a+b-0,5\cos^2\theta)\lambda'\lambda^{-1}\rho + \sum_{s+k=2}^{m} \text{Re}\Big[B_{s,k}(t;a,b)\exp(i\theta(s-k-1))\Big]\rho^{s+k} + \Phi_1,$$

$$(5)$$

$$\theta' = \lambda^{0,25} + 0,25\lambda'\lambda^{-1}\sin 2\theta + \sum_{s+k=2}^{m} \text{Im}\Big[B_{s,k}(t;a,b)\exp(i\theta(s-k-1))\Big]\rho^{s+k-1} + \rho^{-1}\Phi_2,$$

where $\Phi_1 \equiv \text{Re}\Big[\Phi^* \exp(-i\theta)\Big]$, $\Phi_2 \equiv \text{Im}\Big[\Phi^* \exp(-i\theta)\Big]$, $|\Phi_s| \leq L^*(t;a,b)\rho^{m+\alpha}$, s=1,2.

Proof is obvious.

Remark 1. The following estimate

$$\lambda^{-0,25} \min\{\lambda^{a+0,25}, \lambda^{b-0,25}\} \rho \le S(t,\lambda,a,b) \le 2\lambda^{-0,25} \left(\lambda^{a+0,25} + \lambda^{b-0,25}\right) \rho \tag{6}$$

is implied by transformations (2), (4).

3. Main Results

It should be noted that the behavior of the value $S(t, \lambda, a, b)$ depends on solutions of the first d.e. of the d.s. (5), as implied by the estimate (6). To understand the behavior of these solutions we shall note that there is a group of terms which don't depend of θ . This allows to obtain the from the differential system (5) a d.e. of the type

$$\rho' = \sum_{s=1}^{m_0} \operatorname{Re} B_{s+1,s}(t; a, b) \rho^{2s+1}, \tag{7}$$

the behavior of all solutions of which can by investigated by using the method [2].

Theorem 1. Let for the d.e. (1) there are $a, b \in \mathbf{R}$ such that

1) among the functions
$$\left[-2s\int_{t_0}^{t} \operatorname{Re} B_{s+1,s}(\tau;a,b) d\tau\right]^{-\frac{1}{2s}}$$
, $\left[-\operatorname{Re} B_{s+1,s}(t;a,b)\operatorname{Re}^{-1} B_{k+1,k}(t;a,b)\right]^{\frac{1}{2(k-s)}}$, $s \neq k$, $s,k = \overline{1,m_0}$,

there is $\phi(t; a, b) : \Delta \mapsto \mathbf{R}_+$ such that there exists

$$\Lambda(t; a, b) \equiv \max\{(a+b)\lambda'\lambda^{-1} + \phi'(t; a, b)\phi^{-1}(t; a, b) - 0, 5|\lambda'|\lambda^{-1},$$

$$\operatorname{Re} B_{s+1,s}(t; a, b)\phi^{2s}(t; a, b); \ s = \overline{1, m_0}\},$$

and

$$[-(a+b)\lambda'\lambda^{-1} - \phi'(t;a,b)\phi^{-1}(t;a,b) + 0.5|\lambda'|\lambda^{-1}]x + \sum_{s=1}^{m_0} \operatorname{Re} B_{s+1,s}(t;a,b)\phi^{2s}(t;a,b)x^{2s+1}$$

$$\equiv \Lambda(t;a,b) \sum_{s=0}^{m_0} \left[B_{2s+1}(a,b) + o_{2s+1}(1) \right] x^{2s+1}, \ B_{2s+1}(a,b) \in \mathbf{R}, \ s = \overline{0,m_0};$$

2) there is
$$c_0 \in \mathbf{R}_+$$
 such that $\sum_{s=0}^{m_0} B_{2s+1}(a,b) c_0^{2s+1} \in \mathbf{R}_-$, and

$$\phi^{-1}(t, a, b)G[t, a, b, \phi(t, a, b)c_0] = o(1), t \uparrow \omega$$

$$\left(\sup_{t\in\mathbf{\Delta}}\phi^{-1}(t,a,b)G[t,a,b,\phi(t,a,b)c_0] \le -\sum_{s=0}^{m_0}B_{2s+1}(a,b)c_0^{2s+1}\right);$$

3) $\lambda^{-0.25}(\lambda^{a+0.25} + \lambda^{b-0.25})\phi(t;a,b) = o(1), t \uparrow \omega$. Then it has the property $AsSt_{\lambda}$ $(G_{\Delta}AsSt_{\lambda})$ as $t \uparrow \omega$.

Proof. For the first d.e. of the d.s. (5) we make the transformation

$$\rho = \phi x \tag{8}$$

which, under the condition 1), reduces it to a d.e. of the type

$$x' = \Lambda(t; a, b) \left\{ \sum_{s=0}^{m_0} B_{2s+1}(a, b) x^{2s+1} + \phi^{-1}(t, a, b) G^*[t; a, b, \theta, \phi(t, a, b) x] \right\}, \tag{9}$$

where we have the estimate $|G^*[t;a,b,\theta,\phi(t,a,b)x]| \leq G[t,a,b,\phi(t,a,b)x]$ for all $\theta \in \mathbf{R}, t \in \Delta$. Then, under the condition 2), there is $T_0 \in \Delta$ such that if $x = c_0$ for all $t \in [T_0,\omega]$, then we have the inequality x' < 0. It means that any solution $x = x(t;t_0^*,\theta_0,x_0)$ of the d.e. (9) with a sufficiently small initial value x_0 is bounded for all $\theta \in \mathbf{R}$ and $t \in [t_0^*,\omega[,t_0^*\in [T_0,\omega]]$.

Using condition 3) and substitution (8) we see that smallness of the value x corresponds to smallness of the value $S(t, \lambda, a, b)$.

Remark 2. It follows from condition 2) of Theorem 1 that the coefficients $\operatorname{Re} B_{s,k}(t,a,b)$, $s \neq k+1, s, k = \overline{1,m}$, of the first d.e. of the d.s. (5) must be small with respect to the coefficients $\operatorname{Re} B_{s+1,s}(t,a,b)$, $s=\overline{1,s_0}$, of this d.e. If this condition doesn't hold, then the order of growth of these coefficients can be decreased if the method of nonlinear "frozen" transformations [3] is applied to the d.e. (4).

Lemma 3. Transformations (2) and

$$x = z + H(t, z, \overline{z}) \equiv z + \sum_{s+k}^{m} h_{sk} z^{s} \overline{z}^{k}, \quad z = \rho \exp(i\theta), \tag{10}$$

where ρ , θ are polar coordinates reduce the d.e. (1) to the d.s. of the type

$$\rho' = -(a+b-0,5\cos^2\theta)\lambda'\lambda^{-1}\rho + \sum_{s=1}^{m_0} A_{2s+1}(t,a,b)\rho^{2s+1} + \Phi_1^*(t,a,b,\theta,\rho),$$

$$\theta' = \lambda^{0,5} + \sum_{s=0}^{m_0} B_{2s+1}^*(t,a,b)\rho^{2s} + 0,25\lambda'\lambda^{-1}\sin 2\theta + \Phi_2^*(t,a,b,\theta,\rho),$$
(11)

for which $A_{2s+1}(t,a,b)$, $B_{sk+1}^*(t,a,b)$ are known real functions of t only, $s=\overline{1,m_0}$, $\Phi_k^*(t,\theta,\rho)$, k=1,2, are known real 2π -periodic in θ functions, $\Phi_k^*(t,\theta,0)\equiv 0$, k=1,2.

Proof. First let us apply the transformation (2) to the d.e. (1). And next, the transformation (10) is applied to the obtained d.e. (1), where h_{rl} , $r+l=\overline{2,m}$, are defined such that the d.e. in z in the autonomous case will have the type $z'=i\lambda^{\frac{1}{2}}z$.

For the forms $H_k \equiv \sum_{r+l=k} h_{rl} z^r \overline{z}^l$, $k = \overline{2, m}$, we have the d.e.

$$-\frac{\partial H_{k}}{\partial t} + H_{k} - z \frac{\partial H_{k}}{\partial z} + \overline{z} \frac{\partial H_{k}}{\partial \overline{z}}$$

$$= i\lambda_{1}^{-\frac{1}{2}} \left[F_{k}(t, z, \overline{z}) + \sum_{s=2}^{k-1} F_{s} \left(t, z + \sum_{j=2}^{m} H_{j}, \overline{z} + \sum_{j=2}^{m} \overline{G_{j}} \right) - \sum_{j=2}^{k-1} \left(F_{k-j+1} \frac{\partial H_{j}}{\partial z} - \overline{F}_{k-j+1} \frac{\partial H_{j}}{\partial \overline{z}} \right) \right]$$

$$+ \sum_{j=2}^{k-1} \left(H_{k-j+1} \frac{\partial H_{j}}{\partial x} - \overline{H_{k-j+1}} \frac{\partial H_{j}}{\partial \overline{z}} \right), \ k = \overline{2, m}, \tag{12}$$

where $F_k(t,z,\overline{z}) \equiv \sum_{l,l,l} B_{r,l} z^r \overline{z}^l, k = \overline{2,m}.$

We can't solve the d.e. (12) exactly. Therefore we use the method of "frozen" t and replace this d.e. by an algebraic equation of the type

$$H_{k} - z \frac{\partial H_{k}}{\partial z} + \overline{z} \frac{\partial H_{k}}{\partial \overline{z}} = i\lambda_{1}^{-\frac{1}{2}} \left[F_{k}(t, z, \overline{z}) + \sum_{s=2}^{k-1} F_{s} \left(t, z + \sum_{j=2}^{m} H_{j}, \overline{z} + \sum_{j=2}^{m} \overline{H_{j}} \right) \right]$$

$$- \sum_{j=2}^{k-1} \left(F_{k-j+1} \frac{\partial H_{j}}{\partial x} - \overline{F}_{k-j+1} \frac{\partial H_{j}}{\partial \overline{x}} \right) + \sum_{j=2}^{k-1} \left(H_{k-j+1} \frac{\partial H_{j}}{\partial x} - \overline{H_{k-j+1}} \frac{\partial H_{j}}{\partial \overline{x}} \right)$$

$$+ z \sum_{s=2}^{k-1} \left(\frac{\partial H_{s}}{\partial x} \frac{\partial H_{k-s+2}}{\partial \overline{z}} - \frac{\partial H_{s}}{\partial \overline{z}} \frac{\partial \overline{H}_{k-s+2}}{\partial z} \right), \quad k = \overline{2, m}.$$

$$(13)$$

If in the right-hand side of the d.e. (13) we shall denote by A_{rl}^{**} the coefficient at $z^r \overline{z}^l$, then for h_{rl} , r+l=k, $k=\overline{2,m}$, we shall obtain the d.e. of the type

$$(1 - r + l)h_{rl} = A_{rl}^{**}, \quad r + l = k, \ k = \overline{2, m}.$$
 (14)

It's easy to understand that the d.e. (14) does not have a solution only if r = l + 1. In this case we define $h_{l+1,l} \equiv 0$.

As the result of applying transformations (2), (10) to the d.e. (1), the d.s. (10) will have a polynomial in ρ the coefficients of which depend only on t. This allows to select the d.e. of the type

$$\rho' = \sum_{s=1}^{m_0} A_{2s+1}(t, a, b) \rho^{2s+1}, \tag{15}$$

the behavior of regular solutions of which can determine λ -stability of the d.e. (1).

Since the substitution (10) has θ under the signs of \sin and \cos , to get conditions for properties St_{λ} , $AsSt_{\lambda}$ to hold for the d.e. (1), it is sufficient to investigate the properties of solutions of the first d.e. (11) relatively to ρ for any variation of $\theta \in \mathbf{R}$.

Theorem 2. Let for the d.e. (1) there are $a, b \in \mathbf{R}$ such that

- 1) for the d.s. (11) there exists a solution of the Cauchy problem;
- 2) among the functions

$$\left[-2s\int_{t_0}^t A_{2s+1}(\tau,a,b)d\tau\right]^{-\frac{1}{2s}}, \left[-A_{2s+1}^{-1}(t,a,b)A_{2k+1}(t,a,b)\right]^{\frac{1}{2(s-r)}}, s,k=\overline{1,m_0}, s\neq k,$$

there exists $\phi(t, a, b) : \mathbf{\Lambda} \mapsto \mathbf{R}_+$ such that there is

$$\Lambda(t; a, b) = \max\{(a+b)\lambda'\lambda^{-1} + \phi'(t; a, b)\phi^{-1}(t; a, b) - 0, 5|\lambda'|\lambda^{-1}, A_{2s+1}(t; a, b)\phi^{2s}(t; a, b); s = \overline{1, m_0}\}$$

and

$$-(a+b)\lambda'\lambda^{-1} - \phi'(t;a,b)\phi^{-1}(t;a,b) + 0, 5|\lambda'|\lambda^{-1}]z + \sum_{s=1}^{m_0} A_{2s+1}(t;a,b)\phi^{2s}(t;a,b)z^{2s+1}$$

$$\equiv \Lambda(t;a,b) \sum_{s=0}^{m_0} \left[A_{2s+1}^*(a,b) + o_{2s+1}(1) \right] x^{2s+1}, \quad A_{2s+1}^*(a,b) \in \mathbf{R}, \ s = \overline{0,m_0};$$

3) there exists a constant
$$c_0 \in \mathbf{R}_+$$
 such that $\sum_{s=0}^{m_0} A_{2s+1}^*(a,b) c_0^{2s+1} \in \mathbf{R}_-$ and

$$\Lambda^{-1}(t,a,b)\phi^{-1}(t,a,b)\Phi_1^*[t,a,b,\theta,\phi(t,a,b)c_0)] \,=\, o(1)\text{, }t\uparrow\omega\text{, for all }\theta\in\mathbf{R}$$

$$\left(\sup_{t\in\mathbf{\Delta},\theta\in\mathbf{R}}\left|\Lambda^{-1}(t,a,b)\Phi_1^{**}(t,a,b,\theta)-\sum_{s=0}^{m_0}A_{2s+1}^*c_0^{2s+1}\right|<-\sum_{s=0}^{m_0}A_{2s+1}^*c_0^{2s+1},\right.$$

$$\Phi_1^{**}(t, a, b, \theta) \equiv -\left[(a + b - 0.5\cos^2 \theta) \lambda' \lambda^{-1} + \phi'(t, a, b) \phi^{-1}(t, a, b) \right] c_0$$

$$+ \sum_{s=1}^{m_0} A_{2s+1}(t, a, b) \phi^{2s}(t, a, b) c_0^{2s+1}$$

$$+ \phi^{-1}(t, a, b) \Phi_1^*[t, a, b, \theta, \phi(t, a, b) c_0] ;$$

4) $\lambda^{-0.25}(\lambda^{a+0.25} + \lambda^{b-0.25})\phi(t; a, b) = o(1), h_{sk}(t, a, b)\phi^{s+k-1}(t, a, b) = O(1), t \uparrow \omega, s+k = \overline{2, m}.$

Then it has the property $AsSt_{\lambda}$ ($G_{\Delta}AsSt_{\lambda}$) as $t \uparrow \omega$.

Proof. For the first d.e. of the d.e. (11) we apply the substitution $z = \phi(t, a, b)v$. And to the obtained d.e. for v we apply Theorem 1.

For the sake of clarity of the obtained results, let us consider the d.e. (1) in a special case. Let, for the d.e. (1),

$$\omega = +\infty, \ m = 3, \ \int_{-\infty}^{+\infty} \lambda^{0.5} dt = +\infty, \tag{16}$$

and there are $a, b \in \mathbf{R}$ such that there exist finite limits

$$\lim_{t \to +\infty} \lambda^{(k-1)(a+b)-0,5(s+1)} f_{s,k-s}, \quad 0 \le s \le k, \quad k = 2,3.$$
(17)

Then the substitution (2) transforms it into d.e. (3) for which

$$B_{20}(t, a, b) \equiv \overline{B}_{02}(t, a, b) \equiv 0,5\lambda^{a+b} \left(\lambda^{-1} f_{20} - i\lambda^{-0.5} f_{11} + f_{02}\right),$$

$$B_{11}(t, a, b) \equiv -\lambda^{a+b} \left(\lambda^{-1} f_{20} - f_{02}\right),$$

$$B_{30}(t,a,b) \equiv \overline{B}_{03}(t,a,b) \equiv 0,5\lambda^{2(a+b)} \left(i\lambda^{-1,5} f_{30} - \lambda^{-1} f_{21} - i\lambda^{-0,5} f_{12} + f_{03} \right),$$

$$B_{21}(t,a,b) \equiv \overline{B}_{12}(t,a,b) \equiv -0.5\lambda^{2(a+b)} \left(3i\lambda^{-1.5} f_{30} - \lambda^{-1} f_{21} + i\lambda^{-0.5} f_{12} - 3f_{03} \right).$$

Let us apply the transformation

$$x = z + H, H \equiv H_2 + H_3, H_k \equiv \sum_{s=0}^{k} h_{k-s,s}(t,a,b) z^{k-s} \overline{z}^s, k = 2,3,$$
 (18)

to d.e. (3) where the forms H_2 , H_3 are defined so that, in the autonomous case, the d.e. for z has the form $z' = i\lambda^{0.5}z$. Under this condition, the forms H_2 , H_3 satisfy a d.e. of the form

$$-\frac{\partial H_2}{\partial t} + i\lambda^{\frac{1}{2}} \left(H_2 - z \frac{\partial H_2}{\partial z} + \overline{z} \frac{\partial H_2}{\partial \overline{z}} \right) + \sum_{s=0}^{2} B_{2-s,s} z^{2-s} \overline{x}^s = 0,$$

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$$-\frac{\partial H_3}{\partial t} + i\lambda^{0,5} \left(H_3 - z \frac{\partial H_3}{\partial z} + \overline{z} \frac{\partial H_3}{\partial \overline{z}} \right) + \sum_{s=0}^{3} B_{3-s,s} z^{3-s} \overline{z}^s$$

$$+ [\overline{B}_{02} h_{11} + B_{11} \overline{h}_{02} - i\lambda^{0,5} (2h_{20}^2 - h_{11} \overline{h}_{02})] z^3$$

$$+ [B_{20} h_{11} + B_{11} \overline{h}_{11} - B_{11} h_{20} + 2B_{02} \overline{h}_{02} + \overline{B}_{11} h_{11} + 2\overline{B}_{02} h_{02}$$

$$- i\lambda^{0,5} (2h_{11} h_{02} + h_{20} h_{11} - |h_{11}|^2) - 2|h_{02}|^2] z^2 \overline{z}$$

$$+ [2B_{20} h_{02} + B_{11} \overline{h}_{20} + 2B_{02} \overline{h}_{11} - 2B_{02} h_{20} + \overline{B}_{20} h_{11} + 2\overline{B}_{11} h_{02}$$

$$- i\lambda^{0,5} (h_{11}^2 + 2h_{20} h_{02} - \overline{h}_{20} h_{11} - 2\overline{h}_{11} h_{02})] z \overline{z}^2$$

$$+ [B_{11} h_{02} + 2B_{02} \overline{h}_{20} - B_{02} h_{11} + 2\overline{B}_{20} h_{02} - i\lambda^{0,5} (h_{11} h_{02} - 2\overline{h}_{20} h_{02})] \overline{z}^3 = 0.$$

Applying the method of the "frozen" t to the obtained d.e. we find the coefficients h_{rl} , r+l=2,3, i.e.

$$h_{20}(t,a,b) \equiv -0.5i\lambda^{a+b-0.5} \left(\lambda^{-1}f_{20} - i\lambda^{-0.5}f_{11} + f_{02}\right),$$

$$h_{11}(t,a,b) \equiv -\lambda^{a+b-0.5} \left(\lambda^{-1}f_{20} - f_{02}\right), \quad h_{02}(t,a,b) \equiv \frac{1}{3}\overline{h}_{20}(t,a,b),$$

$$h_{30}(t,a,b) \equiv -0.25i\lambda^{2(a+b)-0.5} \left(i\lambda^{-1.5}f_{30} - \lambda^{-1}f_{21} - i\lambda^{-0.5}f_{12} + f_{03}\right)$$

$$-\frac{1}{12}\lambda^{2(a+b)-1} \left(\lambda^{-1}f_{20} - i\lambda^{-0.25}f_{11} + f_{02}\right) \left(4\lambda^{-1}f_{20} - 3i\lambda^{-0.5}f_{11} + 2f_{02}\right),$$

$$h_{21}(t,a,b) \equiv 0,$$

$$h_{12}(t,a,b) = -0.25i\lambda^{2(a+b)-0.5} \left(3i\lambda^{-1.5}f_{30} - \lambda^{-1}f_{21} + i\lambda^{-0.5}f_{12} - 3f_{30}\right)$$

$$-\frac{1}{6}\lambda^{2(a+b)-1} \left(\lambda^{-1}f_{20} + i\lambda^{-0.5}f_{11} + f_{02}\right) \left(8\lambda^{-1}f_{20} + 5i\lambda^{-0.5}f_{11} - 12f_{20}\right),$$

$$h_{03}(t,a,b) = 0.25i\lambda^{2(a+b)-0.5} \left(i\lambda^{-1.5}f_{03} + \lambda^{-1}f_{21} - i\lambda^{-0.5}f_{12} - f_{03}\right)$$

$$-\frac{1}{12}\lambda^{2(a+b)-1} \left(\lambda^{-1}f_{20} + i\lambda^{-0.5}f_{11} + f_{02}\right)^{2}.$$

It is easy to see that, under the condition (17), the coefficients of the transformation (18) have the property: there exist finite limits $\lim_{t\to+\infty}h_{sk}=h_{sk}^*$, s+k=2,3, where $h_{sk}-h_{sk}^*\equiv\omega_{sk}=o(1),t\to+\infty,s+k=2,3$.

It means that there exists $z_0 \in \mathbf{R}_+$ such that

$$\sup_{t \in \mathbf{\Delta}, |z| \leq z_0} \left| \frac{\partial H}{\partial z} + \frac{\partial \overline{H}}{\partial \overline{z}} + \frac{\partial H}{\partial z} \frac{\partial \overline{H}}{\partial \overline{z}} - \frac{\partial H}{\partial \overline{z}} \frac{\partial \overline{H}}{\partial z} \right| < 1,$$

i.e., the transformation (18) exists and it is nonsingular.

Then the d.e. (15) has the form

$$\rho' = \lambda^{0.5} A_3(t, a, b) \rho^3,$$

where

$$A_3(t,a,b) \equiv 0.5\lambda^{2(a+b)-0.5}(\lambda^{-1}f_{21}+3f_{03}) - \frac{1}{6}\lambda^{2(a+b)-1.5}f_{11}(\lambda^{-1}f_{20}-f_{02}),$$

moreover under the condition (17) there exists the finite limit $\lim_{t\to +\infty}A_3^*=A_3^0$. Therefore under the condition $A_3^0<0$, the function $\phi(t,a,b)$ from Theorem 2 has the form

$$\phi(t,a,b) \equiv \psi(t) \equiv \left(1 - 2A_3^0 \int_{t_0}^t \lambda^{0.5} d\tau\right)^{-0.5}.$$

From the condition (16) it follows that $\phi(t) = o(1), t \to +\infty$. The function $\Phi_1^*(t, a, b, \theta, \rho)$ from d.s. (11) has the form

$$\Phi_1^*(t, a, b, \theta, \rho) \equiv \operatorname{Re}\left[\exp(i\theta)\Psi(t, a, b, \theta, \rho)\right] - A_3^0 \lambda^{0.5} \rho^3 + \left(a + b - \frac{1}{2}\cos^2\theta\right) \lambda' \lambda^{-1} \rho,$$

where

$$\begin{split} \Psi(t,a,b,\theta,\rho) &\equiv \left(1 + \frac{\partial H}{\partial z} + \frac{\partial \overline{H}}{\partial \overline{z}} + \frac{\partial H}{\partial z} \frac{\partial \overline{H}}{\partial \overline{z}} - \frac{\partial H}{\partial \overline{z}} \frac{\partial \overline{H}}{\partial z}\right)^{-1} \bigg|_{z=\rho \exp(i\theta)} \\ &\times \left\{ \left[\Psi^*(t,a,b,z+H) - \frac{\partial H}{\partial t} \right] \left(1 + \frac{\partial \overline{H}}{\partial \overline{z}}\right) \right. \\ &\left. - \left[\overline{\Psi^*}(t,a,b,z+H) - \frac{\partial \overline{H}}{\partial t} \right] \frac{\partial H}{\partial \overline{z}} \right\} \bigg|_{z=\rho \exp(i\theta)}, \end{split}$$

$$\Psi^*(t, a, b, x) \equiv [i\lambda^{0,25} - (a+b-0, 25)\lambda'\lambda^{-1}]x - 0, 25\lambda'\lambda^{-1}\overline{x} + \sum_{s+k=2}^{3} B_{sk}(t; a, b)x^s\overline{x}^k.$$

Let us assume that

$$\Lambda(t,a,b) \equiv \Lambda(t) = -A_3^0 \lambda^{0,5} \left(2A_3^0 \int_{t_0}^t \lambda^{0,5} d\tau - 1 \right)^{-1}$$

$$\equiv \max \left\{ \left[(a+b)\lambda' - 0, 5|\lambda'| \right] \lambda^{-1} - A_3^0 \lambda^{0,5} \left(1 - 2A_3^0 \int_{t_0}^t \lambda^{0,5} d\tau \right)^{-1}, A_3^0 \lambda^{0,5} \left(1 - 2A_3^0 \int_{t_0}^t \lambda^{0,5} d\tau \right)^{-1} \right\}.$$

Then under the condition of existence of the finite limit

$$\lim_{t \to +\infty} \lambda' \lambda^{-1,5} \int_{t_0}^t \lambda^{0,5} d\tau = B_0 \ge 0,$$

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making the transformation $\rho = \phi(t)x$ we obtain a differential inequality for x in the form

$$x' \le \frac{A_3^0}{2A_3^0 \int_{t_0}^t \lambda^{0,5} d\tau - 1} \left\{ \left[-(a+b)\frac{B_0}{A_3^0} + 0, 5\frac{|B_0|}{A_3^0} + 1 \right] x - x^3 + \Psi^{**}(t, a, b, x) \right\}. \tag{20}$$

Note that if, for example, $\lambda = Bt^{\sigma}$, B = const > 0, then $B_0 = \sqrt{B} > 0$. If, for example, $\lambda = B \ln t$, then $B_0 = 0$.

The positive constant c_0 can be found from the inequality

$$c_0^2 > 1 - (a+b)\frac{B^0}{A_3^0} + 0.5\frac{|B_0|}{A_3^0}.$$

For condition 4) of Theorem 2 to hold, we must require that $\Psi^{**}(t, a, b, c_0) = o(1), t \to +\infty$ in (20). The latter condition is fullfilled if

$$(\omega'_{2-s,s})^2 \lambda^{-1} \int_{t_0}^t \lambda^{0,5} d\tau = o(1), \ \omega'_{3-k,k} \lambda^{-0,5} = o(1), \ t \to +\infty, \ s = 0, 1, 2, \ k = 0, 2, 3,$$

$$\lambda^{(a+b-0,5-1)(m+\alpha)-1} (\lambda^{-0,5} + \lambda^{0,5})^{m+\alpha} \left(\int_{t_0}^t \lambda^{0,5} d\tau \right)^{-0,5\alpha} L = o(1), \quad t \to +\infty.$$

If we consider the behavior of the so-called tail, i.e., the terms powers of which in x equal $4, \ldots, 9$ and which are contained in the function Ψ^{**} , then their coefficients with the factor $\Lambda^{-1}(t)$ disappear for $t \to +\infty$ and x fixed. For example, at x^4 we have

$$B_{20}\phi^{3}(t)\Lambda^{-1}$$

$$= 0.5\lambda^{a+b-0.5}(\lambda^{-1}f_{20} - i\lambda^{-0.5}f_{11} + f_{02})\lambda^{0.5}\left(1 - 2A_{3}^{0}\int_{t_{0}}^{t}\lambda^{0.5}d\tau\right)^{-1.5}$$

$$\times \left(1 - 2A_{3}^{0}\int_{t_{0}}^{t}\lambda^{0.5}d\tau\right)(A_{3}^{0})^{-1}\lambda^{-0.5}$$

$$= i(A_{3}^{0})^{-1}h_{20}\left(1 - 2A_{3}^{0}\int_{t_{0}}^{t}\lambda^{0.5}d\tau\right)^{-0.5} = o(1), \ t \to +\infty,$$

$$B_{30}\phi^{3}(t)\Lambda^{-1}$$

$$= 0, 5\lambda^{2(a+b)-0.5}(i\lambda^{-1.5}f_{30} - \lambda^{-1}f_{21} - i\lambda^{-0.5}f_{12} + f_{03})\lambda^{0.5} \left(1 - 2A_{3}^{0} \int_{t_{0}}^{t} \lambda^{0.5}d\tau\right)^{-1.5} \times \left(1 - 2A_{3}^{0} \int_{t_{0}}^{t} \lambda^{0.5}d\tau\right)(A_{3}^{0})^{-1}\lambda^{-0.5}$$

$$= 2i(A_{3}^{0})^{-1}h_{30}\left(1 - 2A_{3}^{0} \int_{t_{0}}^{t} \lambda^{0.5}d\tau\right)^{-0.5} = o(1), \ t \to +\infty,$$

$$(\omega_{2-s,s}')^2 \lambda^{-1} \int_{t_0}^t \lambda^{0,5} d\tau = o(1), \ \omega_{3-k,k}' \lambda^{-0,5} = o(1), \ t \to +\infty, \ s = 0, 1, 2, \ k = 0, 2, 3,$$

$$\lambda^{(a+b-0,5)(m+\alpha)}\lambda^{0,5}L\left(\int\limits_{t_0}^t\lambda^{0,5}d\tau\right)^{-0,5\alpha}=o(1),\ t\to+\infty.$$

We formulate the obtained results as the following theorem.

Theorem 3. Let the d.e. (1) be such that

1)
$$\omega = +\infty$$
, $m = 3$, $\int_{-\infty}^{+\infty} \lambda^{0.5} dt = +\infty$, the limit $\lim_{t \to +\infty} \lambda' \lambda^{-1.5} \int_{t_0}^{t} \lambda^{0.5} d\tau < +\infty$ exists,

and it's possiple to find $a,b \in \mathbf{R}$ such that there exist finite limits

$$\lim_{t \to +\infty} \lambda^{(k-1)(a+b)-0,5(s+1)} f_{s,k-s}, \ 0 \le s \le k, \ k = 2, 3,$$

and

$$\lim_{t \to +\infty} \left[\lambda^{2(a+b)-0.5} (\lambda^{-1} f_{21} + 3f_{03}) - \frac{1}{6} \lambda^{2(a+b)-1.5} f_{11} (\lambda^{-1} f_{20} - f_{02}) \right] \in \mathbf{R}_{-},$$

$$(h'_{2-s,s})^2 \lambda^{-1} \int_{t_0}^t \lambda^{0.5} d\tau = o(1), \ h'_{3-k,k} \lambda^{-0.5} = o(1), \ t \to +\infty, \ s = 0, 1, 2, \ k = 0, 2, 3$$

 $(h_{sk}, s + k = 2, 3, are defined by formulas (19)),$

$$\lambda^{(a+b-0,5)(m+\alpha-1)-1}(\lambda^{-0,5}+\lambda^{0,5})^{m+\alpha} \left(\int_{t_0}^t \lambda^{0,5} d\tau \right)^{-0,5\alpha} L = o(1), \ t \to +\infty;$$

2)
$$\lambda^{-0.5}(\lambda^{a+0.5} + \lambda^{b-0.5}) \left(\int_{t_0}^t \lambda^{0.5} d\tau \right)^{-0.5} = o(1), \ t \to +\infty.$$

Then it has the property $AsSt_{\lambda}$ as $t \to +\infty$.

Theorem 4. Let for the d.e. (1) there exist $a, b \in \mathbf{R}$ such that 1) for the d.s. (11) there is a solution of the Cauchy problem;

2) among the functions

$$\left[-2s\int_{t_0}^t A_{2s+1}(\tau,a,b)d\tau\right]^{-\frac{1}{2s}}, \ \left[-A_{2s+1}^{-1}(t,a,b)A_{2k+1}(t,a,b)\right]^{\frac{1}{2(s-r)}}, \ s,k=\overline{1,m_0}, \ s\neq k,$$

there is $\phi(t, a, b) : \mathbf{\Lambda} \mapsto \mathbf{R}_+$ such that there exists

$$\Lambda(t; a, b) = \max \left\{ (a+b)\lambda'\lambda^{-1} + \phi'(t; a, b)\phi^{-1}(t; a, b) + 0, 5|\lambda'|\lambda^{-1}, A_{2s+1}(t; a, b)\phi^{2s}(t; a, b); \ s = \overline{1, m_0} \right\}$$

and

$$-[(a+b)\lambda'\lambda^{-1} + \phi'(t;a,b)\phi^{-1}(t;a,b) + 0,5|\lambda'|\lambda^{-1}]z$$

$$+ \sum_{s=1}^{m_0} A_{2s+1}(t;a,b)\phi^{2s}(t;a,b)z^{2s+1}$$

$$\equiv \Lambda(t;a,b) \sum_{s=0}^{m_0} \left[A_{2s+1}^*(a,b) + o_{2s+1}(1) \right] x^{2s+1},$$

$$\int_{s=0}^{\omega} \Lambda dt = +\infty, \quad A_{2s+1}^*(a,b) \in \mathbf{R}, \ s = \overline{0,m_0};$$

3) there exists a constant $c_0 \in]0,1]$ such that for all $t \in \Delta$, $\theta \in \mathbb{R}$, $z \in]0,c_0]$,

$$\sum_{s=0}^{m_0} A_{2s+1}^*(a,b) z^{2s+1} > 0,$$

$$\left| \Lambda^{-1}(t,a,b) \Phi_1^{**}[t,a,b,\theta,z)] - \sum_{s=0}^{m_0} A_{2s+1}^*(a,b) z^{2s+1} \right| < \sum_{s=0}^{m_0} A_{2s+1}^*(a,b) z^{2s+1},$$

$$\Phi_1^{**}(t, a, b, \theta, z) \equiv -[(a+b)\lambda'\lambda^{-1} + \phi'(t, a, b)\phi^{-1}(t, a, b) + 0, 5|\lambda'|\lambda^{-1}]z$$

$$+ \sum_{s=1}^{m_0} A_{2s+1}(t, a, b)\phi^{2s}(t, a, b)z^{2s+1}$$

$$+ \phi^{-1}(t, a, b)\Phi_1^*[t, a, b, \theta, \phi(t, a, b)z];$$

4) for any $\alpha_0 \in]0, c_0]$ there is a constant $l(\alpha_0) \in \mathbf{R}_+$ such that

$$\inf_{t \in \Delta, \ \theta \in \mathbf{R}, \ z \in [\alpha_0, c_0]} \left| z \exp(i\theta) + \sum_{s+k=2}^m h_{sk}(t, a, b) \phi^{s+k-1}(t, a, b) \exp[i\theta(s-k)] z^{s+k} \right| \ge l(\alpha_0),$$

$$\sup_{t \in \mathbf{\Delta}, \; \theta \in \mathbf{R}, \; z \in [\alpha_0, c_0]} \Lambda^{-1}(t, a, b) |\Phi_1^{**}[t, a, b, \theta, z]| < \inf_{z \in [\alpha_0, c_0]} \sum_{s=0}^{m_0} A_{2s+1}(a, b) z^{2s+1};$$

5) $\lambda^{0,25}(\lambda^{a+0,25} + \lambda^{b-0,25})^{-1}\phi^{-1}(t;a,b) = o(1).$

Then it has the property $UnSt_{\lambda}$ as $t \uparrow \omega$.

Proof. Let us use the left-hand side of inequality (6). In the first d.e. of d.s. (11) we use the substitution $z = \phi(t, a, b)v$. Then we apply Chetaev's theorem [4, p. 199] to the obtained d.e. in v.

To clarity the obtained results we sive, for example, the following theorem.

Theorem 5. Let for the d.e. (1) the condition 1) of Theorem 3 be fulfilled and

$$\lambda^{0,5}(\lambda^{a+0,5} + \lambda^{b-0,5})^{-1} \left(\int_{t_0}^t \lambda^{0,5} d\tau \right)^{0,5} = o(1), \ t \to +\infty.$$

Then it has the property $UnSt_{\lambda}$ as $t \to +\infty$.

Proof. is reduced to a check of conditions of Theorem 4.

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