

DELAYED FEEDBACK MAKES NEURONAL FIRING STATISTICS NON-MARKOVIAN

ЗАТРИМАНИЙ ЗВОРОТНИЙ ЗВ'ЯЗОК СПРИЧИНЯЄ НЕМАРКОВІСТЬ СТАТИСТИКИ ПОСТРІЛІВ НЕЙРОНА

The instantaneous state of a neural network consists of both the degree of excitation of each neuron and the positions of impulses in communication lines between the neurons. In neurophysiological experiments, the neuronal firing moments are registered, but not the state of communication lines. However, future spiking moments depend substantially on the past positions of impulses in the lines. This suggests that the sequence of intervals between firing moments (interspike intervals, ISI) in the network can be non-Markovian. In this paper, we address this question for a simplest possible neural "network", namely, a single neuron with delayed feedback. The neuron receives excitatory input both from the input Poisson process and from its own output through the feedback line. We obtain exact expressions for the conditional probability density $P(t_{n+1} | t_n, \dots, t_1, t_0)dt_{n+1}$ and prove that $P(t_{n+1} | t_n, \dots, t_1, t_0)$ does not reduce to $P(t_{n+1} | t_n, \dots, t_1)$ for any $n \geq 0$. This means that the output ISI stream cannot be represented as a Markov chain of any finite order.

Стан нейронної мережі складається як з величини збудження в кожному з нейронів, так і зі значень положення імпульсів у лініях зв'язку. В нейрофізіологічних експериментах реєструються моменти пострілів окремих нейронів, а не стани ліній зв'язку. Але моменти наступних пострілів істотним чином залежать від положення імпульсів у лініях зв'язку в попередні моменти. Це наводить на думку, що послідовність інтервалів між послідовними пострілами окремого нейрона в мережі (міжспайкові інтервали, МСІ) може складати немарковський точковий стохастичний процес. У цій роботі досліджується така можливість для найпростішої з можливих нейронної „мережі”, а саме, поодинокого нейрона з затриманим зворотним зв'язком. Нейрон отримує в якості стимулу збуджувальні імпульси від пуассонівського вхідного процесу і власні вихідні збуджувальні імпульси через лінію зворотного зв'язку. Одержано точні вирази для щільності умовної ймовірності $P(t_{n+1} | t_n, \dots, t_1, t_0)dt_{n+1}$ і доведено, що $P(t_{n+1} | t_n, \dots, t_1, t_0)$ не зводиться до $P(t_{n+1} | t_n, \dots, t_1)$ для будь-якого $n \geq 0$. Це означає, що вихідний потік МСІ неможливо подати як марковський ланцюг скінченного порядку.

1. Introduction. Activity of many central neurons is seemingly random. This fact allows to describe the firing activity as stochastic process [1, 2]. If a single neuron is considered, which is stimulated with a point renewal process, then the firing activity will be as well renewal¹. We now put a question: Is it feasible that a neuron embedded into a recurrent network will have an activity, which is as well renewal?

In a neural network, the main component parts are neurons and inter-neuronal communication lines — axons [3]. These same units are the main ones in most types of artificial neural networks [4]. If so, then the instantaneous dynamical state of a network must include dynamical states of all the neurons and communication lines the network is composed of. The state of a neuron can be described as its degree of excitation. The state of a line consists of information of whether the line is empty or conducts an impulse. If it does conduct, then further information about how much time is required for the impulse to reach the end of the line (time to live) describes the line's state.

In neurophysiological experiments, the triggering (spiking, firing) moments of individual neurons but not the states of communication lines are registered. The sequence of intervals between the

¹We do not take into account adaptation mechanisms here.

consecutive moments (interspike intervals, ISIs) is frequently considered as a renewal [5] or Markovian [6–8] stochastic process. For a renewal process, the consecutive ISIs are mutually statistically independent. Moreover, all statistical characteristics of a spike train must be derivable from the single-ISI probability distribution. Additionally, those characteristics must be the same for a shuffled spike train, obtained by randomly reordering the ISIs, since shuffling does not change the single-ISI probability distribution. On the other hand, the experimentally obtained spike trains in auditory [9] and visual [10] sensory systems do not support the ISIs' mutual independence. This is revealed by calculating the correlation coefficient between the adjacent ISIs, which appeared to be nonzero for the experimental spike trains, while it must be zero for any renewal process. Also, such characteristics as Fano factor curve and firing rate distribution calculated for shuffled spike trains differ qualitatively from those obtained for the intact ones. These observations can be associated with memory effects in the ISI sequence which arise from an underlying non-renewal process. Recently [11], such a possibility was studied experimentally for weakly electric fish electrosensory afferents using high-order interval analysis, count analysis, and Markov-order analysis. The authors conclude that the experimental evidence cannot reject the null hypothesis that the underlying Markov chain model is of order m or higher, or maybe non-Markovian. The limited data sets used in [11] allow to establish a lower bound for m as $m \geq 7$ for some neural fibers.

What could be possible sources of such non-renewal, or even non-Markovian, behavior in a real neural network? First, this behavior could be inherited from non-renewal (non-Markovian) character of the input signal. Second, intrinsic neuronal properties, such as adaptation, could be responsible.

In this paper, we show that the presence of delayed recurrent neuronal interconnections represents the natural cause of the non-Markovian behavior. For this purpose, we consider the simplest possible neural “net”, namely, a single neuron with delayed feedback, which is driven with Poisson process. As neuronal model we take binding neuron as it allows rigorous mathematical treatment. We study the output ISI stream of this system and prove that it cannot be presented as Markovian chain of any finite order. This suggests that activity of any network with delayed interconnections, if presented in terms of neuronal firing moments, should be non-Markovian as well.

2. The object under consideration. 2.1. Binding neuron model. The understanding of mechanisms of higher brain functions expects a continuous reduction from higher activities to lower ones, eventually, to activities in individual neurons, expressed in terms of membrane potentials and ionic currents. But the description of the higher brain functions in terms of potentials and currents in parts of individual neurons would be difficult, similarly as it would be difficult to describe execution of computer programs by a CPU in terms of Kirhgoff's laws. In this connection, it would be helpful to abstract from the rules by which a neuron changes its membrane potentials to rules by which the input impulse signals are processed in the neuron and determine its output firing activity. The “coincidence detector”, and “temporal integrator” are the examples of such an abstraction, see discussion in [12].

One more abstraction, the binding neuron (BN) model, is proposed as signal processing unit [13], which can operate either as coincidence detector, or temporal integrator, depending on quantitative characteristics of stimulation applied. This conforms with behavior of real neurons, see, e.g., [14, 15]. The BN model describes functioning of a neuron in terms of discrete events, which are input and output impulses, and degree of temporal coherence between the input events, see [16] for detailed

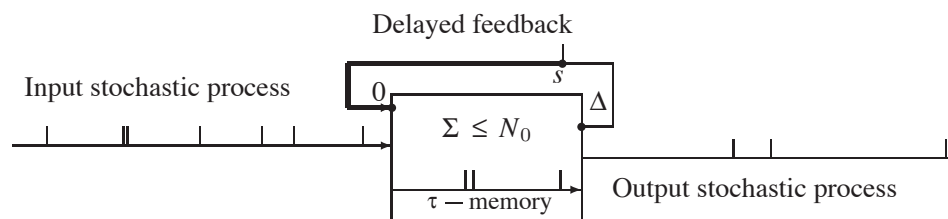


Fig. 1. Binding neuron with feedback line under Poisson stimulation. Multiple input lines with Poisson streams are joined into a single one here. Δ is the delay duration in the feedback line.

description. Mathematically, this model can be realized as follows. We expect that all input impulses in all input lines are identical. Each input impulse is stored in the BN for a fixed time, τ . The τ is similar to the “tolerance interval” discussed in [17]. All input lines are excitatory. The neuron fires an output impulse if the number of stored impulses, Σ , is equal or higher than threshold value, N_0 . After that, BN clears its memory and is ready to receive fresh inputs. That is, every input impulse either disappears contributing to a triggering event, or it is lost after spending τ units of time in the neuron’s internal memory.

The BN model is not general, but somewhat inspired by neurons as integrators up to a threshold. Its name is suggested by binding of features/events in large-scale neuronal circuits [18–20]. Its operational simplicity is provided by the fact that trace of each input impulse entirely disappears after finite time τ . This is in the contrast to more familiar models where the traces (excitatory postsynaptic potentials, EPSP) decay exponentially. E. g., in the leaky integrate-and-fire model, EPSP is mimicked as pure exponential function the traces of which can disappear only after triggering. In the BN model, the EPSP is mimicked as box function of width/duration τ and the traces are stored in the neuron no longer than τ units of time.

Further, we expect that input stream in each input line is the Poisson one with some intensity λ_i . In this case, all input lines can be collapsed into a single one delivering Poisson stream of intensity $\lambda = \sum_i \lambda_i$, see Fig. 1.

For analytic derivation, we use BN with $N_0 = 2$ in order to keep mathematical expressions shorter. It seems, that cases with higher thresholds might be considered with the same approach, but even $N_0 = 3$ without feedback requires additional combinatorial efforts, see [21]. Therefore, cases of higher threshold are tested here only numerically.

As regards real biological neurons, the number of synaptic impulses in the internal memory which is necessary to trigger a neuron, varies from one [22], through fifty [23], to 60–180 [24], and 100–300 [25].

2.2. Feedback line action. In real neuronal systems, a neuron can form synapses from its axonal branches to its own dendritic tree [26–33]. Synapses of this type are called autapses. Some of the neurons forming autapses are known to be excitatory, see [26, 27, 29, 30, 33] for experimental evidence. As a result, the neuron stimulates itself obtaining an excitatory impulse after each firing with some propagation delay. We model this situation assuming that output impulses of BN are fed back into BN’s input with delay Δ . This gives the BN with delayed feedback model, Fig. 1. Impulses

from the feedback line have the same excitatory action on BN as those arrived from the input Poisson stream. Namely, each one of them is stored in the BN's memory for time τ , after which it disappears completely, if not involved in triggering and generating a spike, see Subsection 2.1.

The feedback line either keeps one impulse, or keeps no impulses and cannot convey two or more impulses at the same time. Biological correlates, which support to an extent this assumption, could be a prolonged refractory time and/or short-term synaptic depression. The latter can have the recovery time up to 20 s [34]. If the feedback line is empty at the moment of firing, the output impulse enters the line, and after time interval equal Δ reaches the BN's input. If the line already keeps one impulse at the moment of firing, the just fired impulse ignores the line.

Any output impulse of BN with feedback line may be produced either with impulse from the line involved, or not. We assume that, just after neuronal firing and sending output impulse, the line is never empty. This assumption is self-evident for output impulses produced without impulse from the line, or if the impulse from the line was involved, but entered empty neuron. In the latter case, the second (triggering) impulse comes from the Poisson stream, neuron fires and output impulse goes out as well as enters the empty line. On the other hand, if impulse from the line triggers BN, which already keeps one impulse from the input stream, it may be questionable if the output impulse is able to enter the line, which was just filled with another impulse. We expect it does. This means that the refraction time of biological axon modelled as feedback line does not exceed Δ . Thus, at the beginning of any output ISI, the line keeps impulse with time to live s , where $s \in]0; \Delta]$, or $0 < s \leq \Delta$. In this paper, we consider the case

$$\Delta < \tau \quad (1)$$

in order to keep expressions shorter.

3. Statement of the problem. The input stream of impulses, which drives neuronal activity is stochastic. Therefore, the output activity of our system requires probabilistic description in spite of the fact that both the BN and the feedback line action mechanisms are deterministic. We treat the output stream of BN with delayed feedback as the stationary process². In order to describe its statistics, we introduce the following basic functions:

the joint probability density $P(t_m, t_{m-1}, \dots, t_0)$ for $m + 1$ successive output ISI durations;

the conditional probability density $P(t_m | t_{m-1}, \dots, t_0)$ for output ISI durations; $P(t_m | t_{m-1}, \dots, t_0) dt_m$ gives the probability to obtain an output ISI of duration between t_m and $t_m + dt_m$ provided the previous m ISIs had durations $t_{m-1}, t_{m-2}, \dots, t_0$, respectively.

Here we reproduce definition from [35].

Definition 1. *The sequence of random variables $\{t_j\}$, taking values in Ω , is called the Markov chain of the order $n \geq 0$, if*

$$\forall_{m>n} \forall_{t_0 \in \Omega} \dots \forall_{t_m \in \Omega}: P(t_m | t_{m-1}, \dots, t_0) = P(t_m | t_{m-1}, \dots, t_{m-n}),$$

and this equation does not hold for any $n' < n$. In the case of ISIs one reads $\Omega = \mathbb{R}^+$.

²The stationarity of the output stream results both from the stationarity of the input one and from the absence of time-dependent parameters in the BN model, see Subsection 2.1. In order to ensure stationarity, we also expect that system is considered after initial period sufficient to forget the initial conditions.

In particular, taking $m = n + 1$, we have the necessary condition

$$P(t_{n+1} | t_n, \dots, t_1, t_0) = P(t_{n+1} | t_n, \dots, t_1), \quad t_i \in \Omega, \quad i = 0, \dots, n + 1, \quad (2)$$

required for the stochastic process $\{t_j\}$ to be the n -order Markov chain.

In the next sections we prove the following theorem.

Theorem 1. *The output ISIs stream of BN with delayed feedback under Poisson stimulation cannot be represented as a Markov chain of any finite order.*

4. Proof outline. In order to prove the Theorem 1, we are going to show analytically, that the equality (2) does not hold for any finite value of n , namely, in the exact expression for conditional probability density $P(t_{n+1} | t_n, \dots, t_1, t_0)$, elimination of t_0 -dependence is impossible.

For this purpose we introduce the stream of events (t, s)

$$ts = \{\dots, (t_i, s_i), \dots\},$$

where s_i is the time to live of the impulse in the feedback line at the moment, when ISI t_i starts. We consider the joint probability density $P(t_{n+1}, s_{n+1}; t_n, s_n; \dots; t_0, s_0)$ for realization of $n + 2$ successive events (t, s) , and the corresponding conditional probability density $P(t_{n+1}, s_{n+1} | t_n, s_n; \dots; t_0, s_0)$ for these events.

Lemma 1. *Stream ts is the 1st order Markovian:*

$$\forall_{n \geq 0} \forall_{t_0 > 0} \forall_{s_0 \in]0; \Delta]} \dots \forall_{t_{n+1} > 0} \forall_{s_{n+1} \in]0; \Delta]}:$$

$$P(t_{n+1}, s_{n+1} | t_n, s_n; \dots; t_0, s_0) = P(t_{n+1}, s_{n+1} | t_n, s_n), \quad (3)$$

where $\{t_0, \dots, t_{n+1}\}$ is the set of successive ISIs, and $\{s_0, \dots, s_{n+1}\}$ are the corresponding times to live.

Proof. In the compound event (t_{n+1}, s_{n+1}) , the time to live s_{n+1} always gets its value before than the t_{n+1} does. The value of s_{n+1} can be determined unambiguously from the (t_n, s_n) value (see Subsections 2.2 and 5.2):

$$s_{n+1} = \begin{cases} s_n - t_n, & t_n < s_n, \\ \Delta, & t_n \geq s_n. \end{cases}$$

The only two factors, which determine the next ISI duration, t_{n+1} , are (i) the value of s_{n+1} , and (ii) the behavior of the input Poisson stream under the condition $(t_n, s_n; \dots; t_0, s_0)$ after the moment θ , when the t_{n+1} starts. The s_{n+1} value does not depend on $(t_{n-1}, s_{n-1}; \dots; t_0, s_0)$, see above. As regards the input Poisson stream, condition $(t_n, s_n; \dots; t_0, s_0)$ imposes certain constraints on its behavior before the θ . Namely, if $t_i \neq s_i$ for some $0 \leq i \leq n$, then one can conclude that an input impulse was obtained just at the end of t_i . In the opposite situation, when $t_i = s_i$, one can conclude that in the course of t_i exactly one impulse was obtained from the Poisson stream. But what do we need in the definition of the $P(t_{n+1}, s_{n+1} | t_n, s_n; \dots; t_0, s_0)$, is the conditional probability to obtain input impulses at definite moments after the θ . For a Poisson stream this conditional probability does not depend on conditions before the θ . For example, conditional probability to obtain the first after θ impulse at $\theta + t$ equals $e^{-\lambda t} \lambda dt$, whatever conditions are imposed on the stream before the θ .

Lemma 1 is proved.

In order to find the conditional probability density $P(t_{n+1} | t_n, \dots, t_1, t_0)$, the following steps should be performed:

Step 1. Use the property (3) for calculating joint probability density of events (t, s) :

$$\begin{aligned} P(t_{n+1}, s_{n+1}; t_n, s_n; \dots; t_0, s_0) &= \\ &= P(t_{n+1}, s_{n+1} | t_n, s_n) \dots P(t_1, s_1 | t_0, s_0) P(t_0, s_0), \end{aligned} \quad (4)$$

where $P(t, s)$ and $P(t_n, s_n | t_{n-1}, s_{n-1})$ denote the stationary probability density and conditional probability density (transition probability) for events (t, s) .

Step 2. Represent the joint probability density for successive output ISI durations as marginal probability by integration over variables s_i , $i = 0, 1, \dots, n + 1$:

$$\begin{aligned} P(t_{n+1}, t_n, \dots, t_0) &= \\ &= \int_0^\Delta ds_0 \int_0^\Delta ds_1 \dots \int_0^\Delta ds_{n+1} P(t_{n+1}, s_{n+1}; t_n, s_n; \dots; t_0, s_0). \end{aligned} \quad (5)$$

Step 3. Use the definition of conditional probability density

$$P(t_{n+1} | t_n, \dots, t_1, t_0) = \frac{P(t_{n+1}, t_n, \dots, t_0)}{P(t_n, \dots, t_0)}. \quad (6)$$

Taking into account the Steps 1 and 2, one derives for the joint probability density $P(t_{n+1}, \dots, t_0)$

$$P(t_{n+1}, t_n, \dots, t_0) = \int_0^\Delta ds_0 \dots \int_0^\Delta ds_{n+1} P(t_0, s_0) \prod_{k=1}^{n+1} P(t_k, s_k | t_{k-1}, s_{k-1}). \quad (7)$$

In the next section, we are going to find the exact analytic expressions for probability densities $P(t, s)$ and $P(t_k, s_k | t_{k-1}, s_{k-1})$, and perform the integration in (7). Then we will apply the Step 3, above, to find expressions for the conditional probability density $P(t_{n+1} | t_n, \dots, t_1, t_0)$. It appears, that the conditional probability density has a singular part of the Dirac's δ -function type. This is because the system's dynamics involves discrete events of obtaining impulse by neuron (see below). The presence of δ -functions in (7) requires more exact definition of the integration domain. Namely, it follows from what is said at the end of the Subsection 2.2, that event $(t, 0)$ has zero probability, whereas event (t, Δ) has positive probability for any $t > 0$. Therefore, each integration in (7) should be performed over the half-open interval $]0; \Delta]$.

In order to prove that the equality (2) does not hold for any $n \geq 0$, we use the singular parts only.

5. Main calculations. 5.1. Probability density $P(t, s)$ for events (t, s) . The probability density $P(t, s)$ can be derived as the product

$$P(t, s) = F(t | s) f(s), \quad (8)$$

where $f(s)$ denotes the stationary probability density for time to live of the impulse in the feedback line at the moment of an output ISI beginning, $F(t | s)$ denotes conditional probability density for ISI duration provided the time to live of the impulse in the feedback line equals s at the moment of

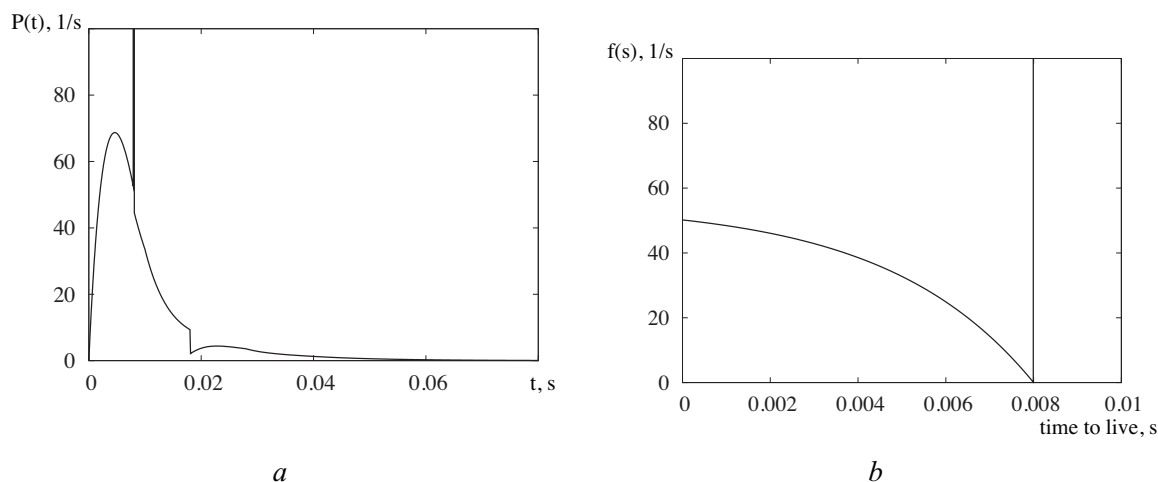


Fig. 2. Output ISI probability density $P(t)$ (a) and probability density $f(s)$ for times to live of the impulse in the feedback line (b), found analytically in [36]. Here $\tau = 10$ ms, $\Delta = 8$ ms, $\lambda = 150$ s⁻¹, $N_0 = 2$. The presence of δ -function in both densities is clearly visible.

this ISI beginning. Exact expressions for both $f(s)$ and $F(t | s)$ are given in [36] (Eqs. (5), (6) and (31)). In this paper we need only singular parts of those expressions, which read:

$$F^{\text{sing}}(t | s) = \lambda s e^{-\lambda s} \delta(t - s), \tag{9}$$

$$f^{\text{sing}}(s) = a \delta(s - \Delta), \quad \text{where } a = \frac{4e^{2\lambda\Delta}}{(3 + 2\lambda\Delta)e^{2\lambda\Delta} + 1}, \tag{10}$$

where a gives the probability to obtain the impulse in the feedback line with time to live equal Δ at the beginning of an arbitrary ISI, λ is the input Poisson stream intensity.

The presence of δ -functions in $F(t | s)$ can be explained as follows. The probability to obtain an output ISI of duration t , which exactly equals s , is not infinitesimally small. Due to (1), it equals to the probability to obtain exactly one impulse from the Poisson stream during time interval $]0; s[$, which is $\lambda s e^{-\lambda s}$. The second impulse comes from the line and triggers the neuron exactly s units of time after the previous triggering. So, we have the non-zero probability to obtain an output ISI, which duration equals exactly s . This gives the δ -function at $t = s$ in the probability density $F(t | s)$.

The probability to have time to live, s , exactly equal Δ at the moment of an output ISI beginning is not infinitesimally small as well. Every time, when the line is free at the moment of triggering, the impulse enters the line and has time to live equal Δ . For the line to be free from impulses at the moment of triggering, it is necessary that $t \geq s$ for the previous ISI. The set of realizations of the input Poisson process, each realization satisfying $t \geq s$, has non-zero probability a , see (10) and [36], and this gives the δ -function at $s = \Delta$ in the probability density $f(s)$.

The output ISI probability density $P(t)$ can be obtained as the result of integration of (8) (see [36] for details):

$$P(t) = \int_0^{\Delta} F(t|s)f(s) ds. \quad (11)$$

Examples of $P(t)$ and $f(s)$ graphs are given in Fig. 2.

5.2. Conditional probability density $P(t_k, s_k | t_{k-1}, s_{k-1})$. Here we find the conditional probability density $P(t_k, s_k | t_{k-1}, s_{k-1})$ for events (t_k, s_k) , which determines the probability to obtain the event (t_k, s_k) , with precision $dt_k ds_k$, provided the previous event was (t_{k-1}, s_{k-1}) . By definition of conditional probabilities, the probability density wanted can be represented as the following product:

$$P(t_k, s_k | t_{k-1}, s_{k-1}) = F(t_k | s_k, t_{k-1}, s_{k-1})f(s_k | t_{k-1}, s_{k-1}), \quad (12)$$

where $F(t_k | s_k, t_{k-1}, s_{k-1})$ denotes conditional probability density for ISI duration, t_k , provided i) this ISI started with time to live of impulse in the feedback line equal to s_k , and ii) previous (t, s) -event was (t_{k-1}, s_{k-1}) ; the $f(s_k | t_{k-1}, s_{k-1})$ denotes conditional probability density for times to live of impulse in the feedback line under condition ii). It is obvious, that

$$F(t_k | s_k, t_{k-1}, s_{k-1}) = F(t_k | s_k), \quad (13)$$

because with s_k being known, the previous event (t_{k-1}, s_{k-1}) does not add any information, useful to predict t_k (compare with the proof of Lemma 1).

In order to find the probability density $f(s_k | t_{k-1}, s_{k-1})$, let us consider various possible relations between t_{k-1} and s_{k-1} . If $t_{k-1} \geq s_{k-1}$, the line will have time to get free from the impulse during the ISI t_{k-1} . That is why, at the beginning of the ISI t_k , an output spike will enter the line and will have time to live $s_k = \Delta$ with probability 1. Therefore, the probability density contains the corresponding δ -function:

$$f(s_k | t_{k-1}, s_{k-1}) = \delta(s_k - \Delta), \quad t_{k-1} \geq s_{k-1}. \quad (14)$$

If $t_{k-1} < s_{k-1}$, then the ISI t_{k-1} ends before the impulse leaves the feedback line. Therefore, at the beginning of the t_k , the line still keeps the same impulse as at the beginning of t_{k-1} . This impulse has time to live being accurately equal to $s_k = s_{k-1} - t_{k-1}$, so

$$f(s_k | t_{k-1}, s_{k-1}) = \delta(s_k - s_{k-1} + t_{k-1}), \quad t_{k-1} < s_{k-1}. \quad (15)$$

Taking all together, for the conditional probability density $P(t_k, s_k | t_{k-1}, s_{k-1})$ one obtains

$$P(t_k, s_k | t_{k-1}, s_{k-1}) = \begin{cases} F(t_k | s_k)\delta(s_k - \Delta), & t_{k-1} \geq s_{k-1}, \\ F(t_k | s_k)\delta(s_k - s_{k-1} + t_{k-1}), & t_{k-1} < s_{k-1}, \end{cases} \quad (16)$$

where exact expression for $F(t | s)$ is given in [36] (Eqs. (5), (6)).

5.3. Joint probability density $P(t_{n+1}, \dots, t_0)$. In this section, we are going to find the exact analytic expression for the joint probability density $P(t_{n+1}, \dots, t_0)$ at the following domain:

$$D_1 = \left\{ (t_0, \dots, t_n) \mid \sum_{i=0}^n t_i < \Delta \right\}. \tag{17}$$

It is worth to notice, that the set of $n + 1$ successive ISI durations t_0, \dots, t_n has non-zero probability, $p_\Delta > 0$, to fall into the domain (17). Indeed, BN with threshold $N_0 = 2$ requires $2(n + 1)$ input impulses within time window $]0; \Delta[$ to be triggered $n + 1$ times within this window (condition (1) ensures that no input impulse will be lost). BN receives impulses both from the Poisson stream and from the feedback line. But no more than one impulse from the line may have time to reach BN's input during time interval less than Δ . Therefore, the other $2n + 1$ impulses must be received from the Poisson stream. On the other hand, if as much as $2(n + 1)$ input impulses are received from the Poisson stream during the time interval $]0; \Delta[$, the inequality (17) holds for sure, no matter was an impulse from the feedback line involved, or not. Therefore, $p_\Delta > p(2n + 2, \Delta) > 0$, where $p(i, \Delta)$ gives the probability to obtain i impulses from the Poisson stream during time interval Δ [37]: $p(i, \Delta) = e^{-\lambda\Delta}(\lambda\Delta)^i/i!$.

For a fixed $(n + 1)$ -tuple $(t_0, \dots, t_n) \in D_1$, let us split the integration domain for s_0 in (7) in the following way:

$$]0; \Delta] =]0; t_0] \cup]t_0; t_0 + t_1] \cup]t_0 + t_1; t_0 + t_1 + t_2] \cup \dots \cup]t_0 + t_1 + \dots + t_n; \Delta],$$

or

$$\int_0^\Delta ds_0 = \int_0^{t_0} ds_0 + \sum_{i=1}^n \int_{\sum_{j=0}^{i-1} t_j}^{\sum_{j=0}^i t_j} ds_0 + \int_{\sum_{j=0}^n t_j}^\Delta ds_0,$$

and introduce the following notations:

$$I_i = \int_{\sum_{j=0}^{i-1} t_j}^{\sum_{j=0}^i t_j} ds_0 \int_0^\Delta ds_1 \dots \int_0^\Delta ds_{n+1} P(t_0, s_0) \times \\ \times \prod_{k=1}^{n+1} P(t_k, s_k \mid t_{k-1}, s_{k-1}), \quad i = 0, 1, 2, \dots, n, \tag{18}$$

$$I_{n+1} = \int_{\sum_{j=0}^n t_j}^\Delta ds_0 \int_0^\Delta ds_1 \dots \int_0^\Delta ds_{n+1} P(t_0, s_0) \prod_{k=1}^{n+1} P(t_k, s_k \mid t_{k-1}, s_{k-1}), \tag{19}$$

where we assume, that $\sum_{j=j_1}^{j_2} = 0$ for $j_1 > j_2$. Domain of s_0 values covered by I_i , $i = 0, \dots, n$, corresponds to the scenario, when impulse, which was in the feedback line at the beginning of ISI t_0 (with time to live s_0), will reach BN during interval t_i , see Fig. 3. In this process, after each firing, which starts ISI t_k , $k \leq i$, the time to live of the impulse in the feedback line is decreased exactly by

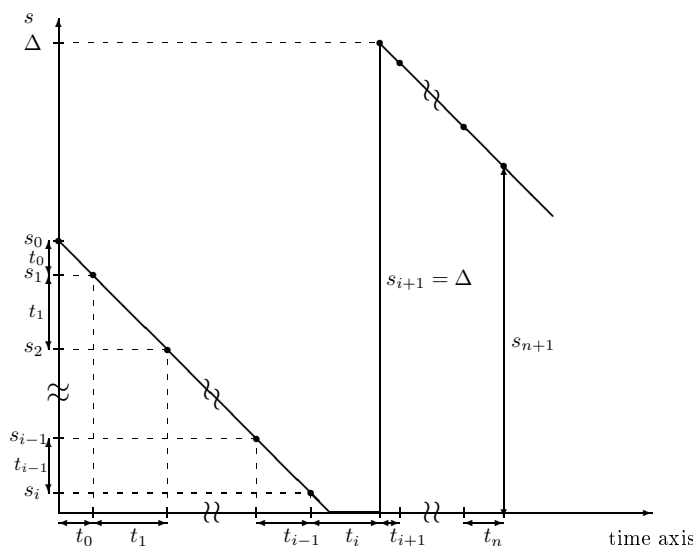


Fig. 3. Illustration of relations between (t_0, \dots, t_n) and (s_0, \dots, s_{n+1}) contributing to the I_i : $s_0 \in \left] \sum_{j=0}^{i-1} t_j; \sum_{j=0}^i t_j \right]$, $\sum_{j=0}^n t_j < \Delta$. The time to live s_k decreases steadily with every output firing for $k = 0, \dots, i - 1$ until it becomes that $s_i < t_i$. Then, during the time interval t_i the line discharges its impulse to BN input, and at the beginning of t_{i+1} starts to convey the new one with time to live $s_{i+1} = \Delta$. After that, times to live s_k are again decreased by corresponding t_k with each firing, $k = i + 1, \dots, n$.

t_{k-1} . This means, that variables of integration $\{s_0, \dots, s_{n+1}\}$, above, are not actually independent, but must satisfy the following relations:

$$s_k = s_0 - \sum_{j=0}^{k-1} t_j, \quad k = 1, \dots, i, \quad (20)$$

which are also ensured by δ -function in the bottom line of (16). Next to s_i time to live must be equal Δ :

$$s_{i+1} = \Delta, \quad (21)$$

and this is ensured by δ -function in the top line of (16). The next to s_{i+1} times to live again are decreased by corresponding ISI with each triggering. Due to (17), this brings about another set of relations

$$s_k = \Delta - \sum_{j=i+1}^{k-1} t_j, \quad k = i + 2, \dots, n + 1, \quad (22)$$

which are again ensured by δ -function in the bottom line of (16). Relations (20), (21) and (22) together with limits of integration over s_0 in (18) ensure that at D_1 the following inequalities hold:

$$\begin{aligned} s_k &> t_k, \quad k = 0, \dots, i - 1, \\ s_i &\leq t_i, \\ s_k &> t_k, \quad k = i + 1, \dots, n. \end{aligned} \quad (23)$$

Inequalities (23) allow one to decide correctly which part of rhs of (16) should replace each transition probability $P(t_k, s_k | t_{k-1}, s_{k-1})$ in (18), and perform all but one integration. This gives

$$\begin{aligned}
 I_i &= \int_{\sum_{j=0}^{i-1} t_j}^{\sum_{j=0}^i t_j} ds_0 \int_0^\Delta ds_1 \dots \int_0^\Delta ds_{n+1} F(t_0 | s_0) f(s_0) \times \\
 &\times \prod_{k=1}^i F(t_k | s_k) \delta \left(s_k - s_0 + \sum_{j=0}^{k-1} t_j \right) F(t_{i+1} | s_{i+1}) \delta(s_{i+1} - \Delta) \times \\
 &\times \prod_{k=i+2}^{n+1} F(t_k | s_k) \delta \left(s_k - \Delta + \sum_{j=i+1}^{k-1} t_j \right) = \\
 &= F \left(t_{n+1} | \Delta - \sum_{j=i+1}^n t_j \right) \dots F(t_{i+2} | \Delta - t_{i+1}) F(t_{i+1} | \Delta) \times \\
 &\times \int_{\sum_{j=0}^{i-1} t_j}^{\sum_{j=0}^i t_j} F \left(t_i | s_0 - \sum_{j=0}^{i-1} t_j \right) \dots F(t_1 | s_0 - t_0) F(t_0 | s_0) f(s_0) ds_0, \quad i = 0, 1, 2, \dots, n. \quad (24)
 \end{aligned}$$

The last expression might be obtained as well by means of consecutive substitution of either top, or bottom line of (16) into (18), without previously discovering (20)–(23).

Finally, integral I_{n+1} corresponds to the case, when at the beginning of interval t_{n+1} , the line still keeps the same impulse as at the beginning of t_0 . Therefore, I_{n+1} comprises the rest of scenarios contributing to the value of $P(t_{n+1}, \dots, t_0)$ in (5). Proceeding as in the preceding terms, the contribution I_{n+1} reads

$$\begin{aligned}
 I_{n+1} &= \int_{\sum_{j=0}^n t_j}^\Delta ds_0 \int_0^\Delta ds_1 \dots \int_0^\Delta ds_{n+1} F(t_0 | s_0) f(s_0) \times \\
 &\times \prod_{k=1}^{n+1} F(t_k | s_k) \delta \left(s_k - s_0 + \sum_{j=0}^{k-1} t_j \right) = \\
 &= \int_{\sum_{j=0}^n t_j}^\Delta F \left(t_{n+1} | s_0 - \sum_{j=0}^n t_j \right) F \left(t_n | s_0 - \sum_{j=0}^{n-1} t_j \right) \dots \\
 &\dots F(t_1 | s_0 - t_0) F(t_0 | s_0) f(s_0) ds_0. \quad (25)
 \end{aligned}$$

Taking into account (24) and (25), one obtains the following expression for joint probability density $P(t_{n+1}, \dots, t_0)$:

$$\begin{aligned}
 P(t_{n+1}, \dots, t_0) &= \sum_{i=0}^{n+1} I_i = \sum_{i=0}^n F(t_{i+1} | \Delta) \prod_{k=i+2}^{n+1} F\left(t_k | \Delta - \sum_{j=i+1}^{k-1} t_j\right) \times \\
 &\times \int_{\sum_{j=0}^{i-1} t_j}^{\sum_{j=0}^i t_j} F(t_0 | s_0) f(s_0) \prod_{k=1}^i F\left(t_k | s_0 - \sum_{j=0}^{k-1} t_j\right) ds_0 + \\
 &+ \int_{\sum_{j=0}^n t_j}^{\Delta} F(t_0 | s_0) f(s_0) \prod_{k=1}^{n+1} F\left(t_k | s_0 - \sum_{j=0}^{k-1} t_j\right) ds_0,
 \end{aligned}
 \tag{26}$$

$$\sum_{i=0}^n t_i < \Delta, \quad n = 0, 1, \dots,$$

where we assume, that $\sum_{j=j_1}^{j_2} = 0$ and $\prod_{j=j_1}^{j_2} = 1$ for $j_1 > j_2$.

The expression (26) gives the joint probability density $P(t_{n+1}, \dots, t_0)$ for consecutive ISI durations at the domain D_1 for an arbitrary n . Therefore, the conditional probability density $P(t_{n+1} | t_n, \dots, t_0)$ at D_1 can be obtained readily, see equation (6).

5.4. Singular part of $P(t_{n+1}, \dots, t_0)$. In order to obtain the singular part of expression, defined in (26), let us first derive singular parts for all $I_i, i = 0, \dots, n$, and I_{n+1} separately. In order to keep the expressions shorter, we represent I_i as follows:

$$I_i(t_0, \dots, t_{n+1}) = X_i(t_0, \dots, t_i) Y_i(t_{i+1}, \dots, t_{n+1}), \quad i = 0, 1, \dots, n,
 \tag{27}$$

where

$$X_i \equiv \int_{\sum_{j=0}^{i-1} t_j}^{\sum_{j=0}^i t_j} F\left(t_i | s_0 - \sum_{j=0}^{i-1} t_j\right) F\left(t_{i-1} | s_0 - \sum_{j=0}^{i-2} t_j\right) \dots F(t_1 | s_0 - t_0) F(t_0 | s_0) f(s_0) ds_0,
 \tag{28}$$

$$Y_i \equiv F\left(t_{n+1} | \Delta - \sum_{j=i+1}^n t_j\right) F\left(t_n | \Delta - \sum_{j=i+1}^{n-1} t_j\right) \dots F(t_{i+2} | \Delta - t_{i+1}) F(t_{i+1} | \Delta).
 \tag{29}$$

At the domain considered, namely, for $\sum_{i=0}^n t_i < \Delta$, the expressions for $F\left(t_n | \Delta - \sum_{j=i+1}^{n-1} t_j\right), \dots, F(t_{i+2} | \Delta - t_{i+1})$ and $F(t_{i+1} | \Delta)$ have no singularities, see (9). Therefore

$$Y_i^{\text{sing}} = F^{\text{sing}}\left(t_{n+1} | \Delta - \sum_{j=i+1}^n t_j\right) F\left(t_n | \Delta - \sum_{j=i+1}^{n-1} t_j\right) \dots F(t_{i+2} | \Delta - t_{i+1}) F(t_{i+1} | \Delta).
 \tag{30}$$

At the same time, integration limits in (28) ensure that $X_i^{\text{sing}} = 0$. Indeed, each integral X_i (and, originally, I_i), $i = 0, 1, \dots, n$, covers the half-open interval $s_0 \in] \sum_{j=0}^{i-1} t_j; \sum_{j=0}^i t_j]$. The only singularity of integrand in (28) at this domain is $\delta \left(\sum_{j=0}^i t_j - s_0 \right)$ which is provided by $F \left(t_i \mid s_0 - \sum_{j=0}^{i-1} t_j \right)$, see (9), and it disappears after integration. Therefore

$$I_i^{\text{sing}} = F^{\text{sing}} \left(t_{n+1} \mid \Delta - \sum_{j=i+1}^n t_j \right) \dots F(t_{i+2} \mid \Delta - t_{i+1}) F(t_{i+1} \mid \Delta) \times$$

$$\times \int_{\sum_{j=0}^{i-1} t_j}^{\sum_{j=0}^i t_j} F \left(t_i \mid s_0 - \sum_{j=0}^{i-1} t_j \right) \dots F(t_1 \mid s_0 - t_0) F(t_0 \mid s_0) f(s_0) ds_0, \quad i = 0, 1, \dots, n. \quad (31)$$

Now, consider the singular part of I_{n+1} , expression (25). Within the integration domain, the integrand contains two singularities: one for $F \left(t_{n+1} \mid s_0 - \sum_{j=0}^n t_j \right)$ at $t_{n+1} = s_0 - \sum_{j=0}^n t_j$ and the other one for $f(s_0)$ at $s_0 = \Delta$, see (9) and (10). After integration over s_0 , the only δ -function survives, which is provided by $F \left(t_{n+1} \mid \Delta - \sum_{j=0}^n t_j \right)$ and located at $t_{n+1} = \Delta - \sum_{j=0}^n t_j$:

$$I_{n+1}^{\text{sing}} = a F^{\text{sing}} \left(t_{n+1} \mid \Delta - \sum_{j=0}^n t_j \right) F \left(t_n \mid \Delta - \sum_{j=0}^{n-1} t_j \right) \dots F(t_1 \mid \Delta - t_0) F(t_0 \mid \Delta), \quad (32)$$

where a is the δ -function's mass in $f(s)$, see (10).

Taking into account (9), (31) and (32), for the singular part of the probability density $P(t_{n+1}, \dots, t_0)$ one obtains

$$P^{\text{sing}}(t_{n+1}, t_n, \dots, t_0) = \sum_{i=0}^{n+1} I_i^{\text{sing}} =$$

$$= \sum_{i=0}^n A_i(t_{i+1}, \dots, t_{n+1}) \delta \left(\sum_{j=i+1}^{n+1} t_j - \Delta \right) + A_{n+1}(t_0, \dots, t_{n+1}) \delta(t_0 + \dots + t_{n+1} - \Delta), \quad (33)$$

$$\sum_{i=0}^n t_i < \Delta,$$

where A_i and A_{n+1} denote regular factors, defined by the following expressions:

$$A_i(t_{i+1}, \dots, t_{n+1}) = \lambda t_{n+1} e^{-\lambda t_{n+1}} F \left(t_n \mid \Delta - \sum_{j=i+1}^{n-1} t_j \right) \dots F(t_{i+2} \mid \Delta - t_{i+1}) F(t_{i+1} \mid \Delta) \times$$

$$\times \int_{\sum_{j=0}^{i-1} t_j}^{\sum_{j=0}^i t_j} F \left(t_i \mid s_0 - \sum_{j=0}^{i-1} t_j \right) \dots F(t_1 \mid s_0 - t_0) F(t_0 \mid s_0) f(s_0) ds_0, \quad i = 0, 1, \dots, n, \quad (34)$$

$$\begin{aligned}
A_{n+1}(t_0, \dots, t_{n+1}) &= a \cdot \lambda t_{n+1} e^{-\lambda t_{n+1}} \times \\
&\times F\left(t_n \mid \Delta - \sum_{j=0}^{n-1} t_j\right) \dots F(t_1 \mid \Delta - t_0) F(t_0 \mid \Delta). \quad (35)
\end{aligned}$$

The presence of δ -functions in joint probability density $P(t_{n+1}, \dots, t_0)$ can be additionally explained as follows. If at the beginning of $(i + 1)$ -th ISI, the impulse enters the line, then output interval t_{n+1} will start with that same impulse in the feedback line with time to live equal $s_{n+1} = \Delta - \sum_{j=i+1}^n t_j$. To trigger BN after time exactly equal s_{n+1} after that, it is necessary to obtain one impulse from the Poisson stream during time interval s_{n+1} . This event has non-zero probability, therefore we have the non-zero probability of an output ISI exactly equal to s_{n+1} : $t_{n+1} = \Delta - \sum_{j=i+1}^n t_j$. This gives the corresponding δ -functions in ISI probability density. The term with $\delta(t_{n+1} + \dots + t_0 - \Delta)$ corresponds to the case, when the impulse enters the line at the beginning of t_0 .

From (6) and (33) one can easily derive the following expression for the singular part of the conditional probability density:

$$\begin{aligned}
P^{\text{sing}}(t_{n+1} \mid t_n, \dots, t_0) &= \frac{1}{P(t_n, \dots, t_0)} \sum_{i=0}^n A_i \cdot \delta\left(\sum_{j=i+1}^{n+1} t_j - \Delta\right) + \\
&+ \frac{A_{n+1}}{P(t_n, \dots, t_0)} \delta(t_0 + \dots + t_{n+1} - \Delta), \quad \sum_{i=0}^n t_i < \Delta, \quad (36)
\end{aligned}$$

where A_i and A_{n+1} are defined in (34) and (35). It should be outlined, that the joint probability density $P(t_n, \dots, t_0)$ has no singularities at the domain $t_n < \Delta - \sum_{i=0}^{n-1} t_i$, see (33) with $(n - 1)$ substituted instead of n .

As one can see, function $P(t_{n+1} \mid t_n, \dots, t_0)$ contains singularity at $t_{n+1} = \Delta - t_n - t_{n-1} - \dots - t_0$. The dependence of the singular part of function $P(t_{n+1} \mid t_n, \dots, t_0)$ on t_0 cannot be compensated by any regular summands, therefore, the whole conditional probability density $P(t_{n+1} \mid t_n, \dots, t_0)$ depends on t_0 . It means, that the condition (2) does not hold for any n for the output stream of BN with delayed feedback.

Theorem 1 is proved.

6. Particular cases. In the previous sections, we have proven the impossibility to represent the stream of output ISI durations for BN with delayed feedback as a Markov chain of any finite order. In particular, output ISI stream is neither a sequence of independent random variables, and therefore is non-renewal, nor it is the first-order Markov process.

In the course of proving Theorem 1 (see Sections 4 and 5), we have obtained the expression for $P(t_{n+1}, t_n, \dots, t_0)$ at the domain $\sum_{i=0}^n t_i < \Delta$ in general case of an arbitrary n , see (26). This allows to calculate the conditional probability density $P(t_{n+1} \mid t_n, \dots, t_0)$ for $\sum_{i=0}^n t_i < \Delta$ and $n = 0, 1, \dots$

In this section, we consider the two particular cases of $P(t_{n+1} \mid t_n, \dots, t_0)$ when $n = 0$ and $n = 1$, namely, the single-ISI conditional probability density $P(t_1 \mid t_0)$ and the double-ISI conditional

probability density $P(t_2 | t_1, t_0)$ and obtain the expressions for $P(t_1 | t_0)$ and $P(t_2 | t_1, t_0)$ for domain (17), as well as for all other possible domains, which were not used in the proof of Theorem 1.

6.1. Conditional probability density $P(t_1 | t_0)$. In order to derive the exact expression for conditional probability density $P(t_1 | t_0)$ for neighbouring ISI durations, we take Steps 1–3, outlined in Section 4, for $n = 0$. In the case of $P(t_1 | t_0)$, there are only three domains, on which the expressions should be obtained separately, namely cases $t_0 < \Delta$, $t_0 > \Delta$ and $t_0 = \Delta$. Performing integration in (7), one obtains the following expressions for $P(t_1, t_0)$ at these domains:

$$P(t_1, t_0) = \begin{cases} F(t_1 | \Delta)P(t_0), & t_0 \geq \Delta, \\ F(t_1 | \Delta) \int_0^{t_0} F(t_0 | s_0)f(s_0) ds_0 + \\ + \int_{t_0}^{\Delta} F(t_1 | s_0 - t_0)F(t_0 | s_0)f(s_0) ds_0, & t_0 < \Delta. \end{cases} \quad (37)$$

Then, by definition of conditional probability densities, one obtains:

$$P(t_1 | t_0) = \begin{cases} F(t_1 | \Delta), & t_0 > \Delta, \\ \frac{1}{P(t_0)} \left(F(t_1 | \Delta) \int_0^{t_0} F(t_0 | s_0)f(s_0) ds_0 + \right. \\ \left. + \int_{t_0}^{\Delta} F(t_1 | s_0 - t_0)F(t_0 | s_0)f(s_0) ds_0 \right), & t_0 < \Delta. \end{cases} \quad (39)$$

It should be outlined, that the output ISI probability density $P(t_0)$ has no singularities at the domain $t_0 < \Delta$. Indeed, due to (9)–(11), the only δ -function contained in $P(t_0)$ is placed at $t_0 = \Delta$, see Fig. 2 (a).

In the vicinity of the point $t_0 = \Delta$, the single-ISI conditional probability density can be derived as

$$P(t_1 | t_0 = \Delta) = \lim_{\epsilon \rightarrow 0} \frac{\int_{\Delta-\epsilon}^{\Delta+\epsilon} dt_0 P(t_1, t_0)}{\int_{\Delta-\epsilon}^{\Delta+\epsilon} dt_0 P(t_0)} = \lim_{\epsilon \rightarrow 0} \frac{\int_{\Delta-\epsilon}^{\Delta+\epsilon} dt_0 P(t_1, t_0)}{\int_{\Delta-\epsilon}^{\Delta+\epsilon} dt_0 a\lambda\Delta e^{-\lambda\Delta} \delta(t_0 - \Delta)}. \quad (41)$$

The integrand in the numerator of (41) also contains singularity at $t_0 = \Delta$ due to the term $P(t_0)$ in (37). Integration in (41) just gives δ -functions' masses both in numerator and denominator, and delivers

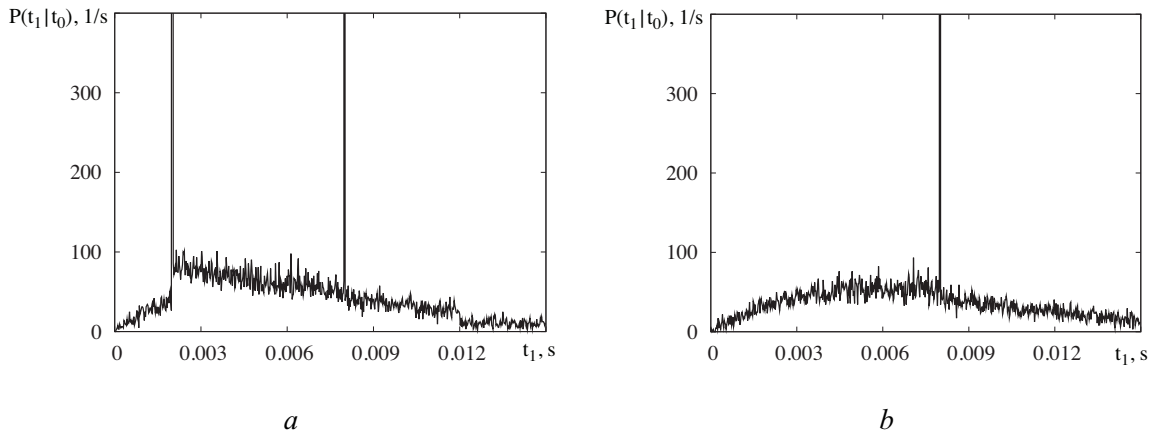


Fig. 4. Conditional probability density $P(t_1 | t_0)$ for $\tau = 10$ ms, $\Delta = 8$ ms, $\lambda = 150 \text{ s}^{-1}$, $N_0 = 2$, $t_0 = 6$ ms (a) and $t_0 = 11$ ms (b), found numerically by means of Monte-Carlo method (the number of firings accounted, $N = 30\,000$). Different course of $P(t_1 | t_0)$ for different t_0 values is clearly visible.

$$P(t_1 | t_0) = F(t_1 | \Delta), \quad t_0 = \Delta. \tag{42}$$

Expressions (39), (40) and (42) can be understood as follows. Since $t_0 \geq \Delta$, one can be sure that the line has time to get free from impulse during t_0 , therefore at the moment of next firing (at the beginning of t_1) the impulse enters the line and has time to live equal Δ . In the case of $t_0 < \Delta$, see (40), two possibilities arise. The first term corresponds to the scenario, when the feedback line discharges conveyed impulse within time interval t_0 , and the second one represents the case when at the beginning of t_1 the line still keeps the same impulse as at the beginning of t_0 .

It can be shown, that the following normalization conditions take place:

$$\int_0^\infty dt_1 P(t_1 | t_0) = 1 \quad \text{and} \quad \int_0^\infty dt_0 P(t_1, t_0) = P(t_1).$$

The singular part of $P(t_1 | t_0)$ can be easily extracted:

$$P^{\text{sing}}(t_1 | t_0) = \begin{cases} e^{-\lambda \Delta} \lambda \Delta \delta(t_1 - \Delta), & t_0 \geq \Delta, \\ \frac{\lambda t_1 e^{-\lambda t_1}}{P(t_0)} \left(\int_0^{t_0} F(t_0 | s_0) f(s_0) ds_0 \delta(t_1 - \Delta) + \right. \\ \left. + a F(t_0 | \Delta) \delta(t_0 + t_1 - \Delta) \right), & t_0 < \Delta. \end{cases} \tag{43}$$

Obviously, expression (44) could be obtained directly from (34)–(36) by substituting $n = 0$.

As it can be seen from (43) and (44), the number of δ -functions in $P(t_1 | t_0)$ and their positions depend on t_0 , therefore the conditional probability density $P(t_1 | t_0)$ cannot be reduced to output ISI probability density $P(t_1)$. Therefore, the neighbouring output ISIs of BN with delayed feedback are correlated, as expected.

Examples of $P(t_1 | t_0)$, found for two domains numerically, by means of Monte-Carlo method (see Section 7 for details), are placed at Fig. 4.

6.2. Conditional probability density $P(t_2 | t_1, t_0)$. In order to derive the exact expression for conditional probability density $P(t_2 | t_1, t_0)$ for the successive ISI durations, we take Steps 1–3, outlined in Section 4, for $n = 1$. In the case of $P(t_2, t_1, t_0)$, there are six domains, on which the expressions should be obtained separately, namely, the domain

$$D_1 = \{t_1, t_0 | t_1 + t_0 < \Delta\},$$

which was already utilized in Section 5, and five remaining:

$$D_2 = \{t_1, t_0 | t_0 \geq \Delta \text{ and } t_1 \geq \Delta\},$$

$$D_3 = \{t_1, t_0 | t_0 < \Delta \text{ and } t_1 \geq \Delta\},$$

$$D_4 = \{t_1, t_0 | t_0 \geq \Delta \text{ and } t_1 < \Delta\},$$

$$D_5 = \{t_1, t_0 | t_0 < \Delta \text{ and } \Delta - t_0 < t_1 < \Delta\},$$

$$d = \{t_1, t_0 | t_0 + t_1 = \Delta\}.$$

In the case, when the exact equality $t_0 + t_1 = \Delta$ holds, namely, if $(t_1, t_0) \in d$, the product $P(t_2 | t_1, t_0) dt_2$ gives the probability to obtain an output ISI of duration within interval $[t_2; t_2 + dt_2]$, provided the overall duration of two previous ISIs accurately equals Δ .

Expressions for $P(t_2 | t_1, t_0)$ can be found exactly on each domain:

$$P(t_2 | t_1, t_0) =$$

$$= \begin{cases} F(t_2 | \Delta), & (t_0, t_1) \in D_2, & (45) \\ F(t_2 | \Delta), & (t_0, t_1) \in D_3, & (46) \\ F(t_2 | \Delta), & (t_0, t_1) \in d, & (47) \\ F(t_2 | \Delta - t_1), & (t_0, t_1) \in D_4, & (48) \\ \frac{1}{P(t_1, t_0)} \left(F(t_2 | \Delta - t_1) F(t_1 | \Delta) \int_0^{t_0} F(t_0 | s_0) f(s_0) ds_0 + \right. \\ \quad \left. + F(t_2 | \Delta) \int_{t_0}^{\Delta} F(t_1 | s_0 - t_0) F(t_0 | s_0) f(s_0) ds_0 \right), & (t_0, t_1) \in D_5, & (49) \\ \frac{1}{P(t_1, t_0)} \left(F(t_2 | \Delta - t_1) F(t_1 | \Delta) \int_0^{t_0} F(t_0 | s_0) f(s_0) ds_0 + \right. \\ \quad \left. + F(t_2 | \Delta) \int_{t_0}^{t_0+t_1} F(t_1 | s_0 - t_0) F(t_0 | s_0) f(s_0) ds_0 + \right. \\ \quad \left. + \int_{t_0+t_1}^{\Delta} F(t_2 | s_0 - t_0 - t_1) F(t_1 | s_0 - t_0) F(t_0 | s_0) f(s_0) ds_0 \right), & (t_0, t_1) \in D_1, & (50) \end{cases}$$

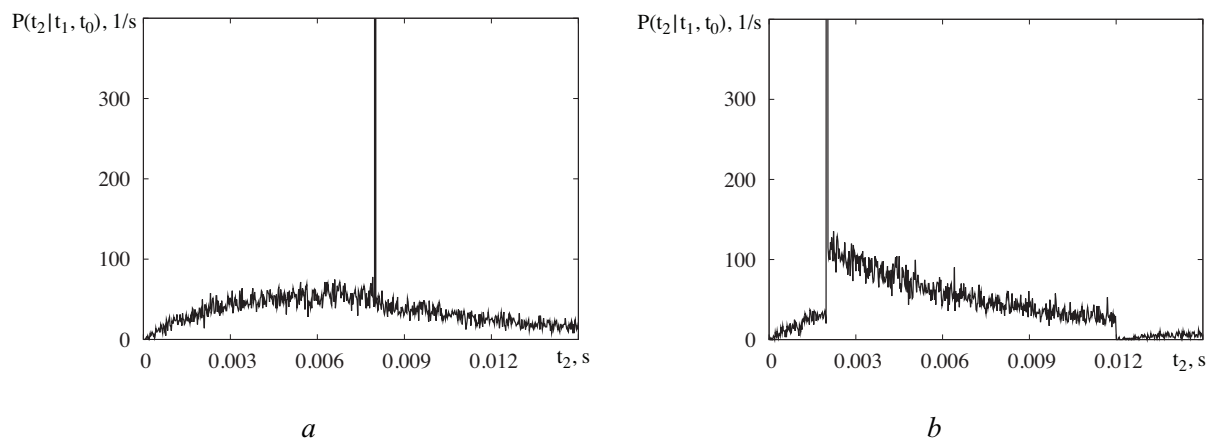


Fig. 5. Conditional probability density $P(t_2 | t_1, t_0)$ for $\tau = 10$ ms, $\Delta = 8$ ms, $\lambda = 150$ s $^{-1}$, $N_0 = 2$, $t_1 = 13$ ms, $t_0 = 13$ ms, $(t_1, t_0) \in D_2$ (a), and $t_1 = 6$ ms, $t_0 = 13$ ms, $(t_1, t_0) \in D_4$ (b), found numerically by means of Monte-Carlo method ($N = 30\,000$).

where

$$P(t_1, t_0) = F(t_1 | \Delta) \int_0^{t_0} F(t_0 | s_0) f(s_0) ds_0 + \int_{t_0}^{\Delta} F(t_1 | s_0 - t_0) F(t_0 | s_0) f(s_0) ds_0,$$

according to (40).

The probability density $P(t_1, t_0)$ contains δ -function at the domain d , see (44). In (47), the double-ISI conditional probability density was derived as

$$P(t_2 | t_1, t_0) = \lim_{\epsilon \rightarrow 0} \frac{\int_{\Delta - t_0 - \epsilon}^{\Delta - t_0 + \epsilon} dt_1 P(t_2, t_1, t_0)}{\int_{\Delta - t_0 - \epsilon}^{\Delta - t_0 + \epsilon} dt_1 P(t_1, t_0)}, \quad (t_0, t_1) \in d, \quad (51)$$

compare with (41). It can be shown, that the numerator in (51) also contains singularity at $t_0 + t_1 = \Delta$. Integration in (51) just gives δ -functions' masses both in numerator and denominator, which gives (47).

It is worth to notice, that $P(t_1, t_0)$ is regular function on both D_1 and D_5 , see denominators in (49) and (50). Indeed, from (43) and (44) one can see, that $P(t_1, t_0)$ may include singularities only at the points $t_1 = \Delta$ and $t_1 = \Delta - t_0$. None of these points belongs to D_1 , or D_5 .

It can be shown, that the following normalization conditions take place:

$$\int_0^{\infty} dt_2 P(t_2 | t_1, t_0) = 1 \quad \text{and} \quad \int_0^{\infty} dt_0 P(t_2, t_1, t_0) = P(t_2, t_1).$$

The singular part of the conditional probability density $P(t_2 | t_1, t_0)$ can be derived as follows:

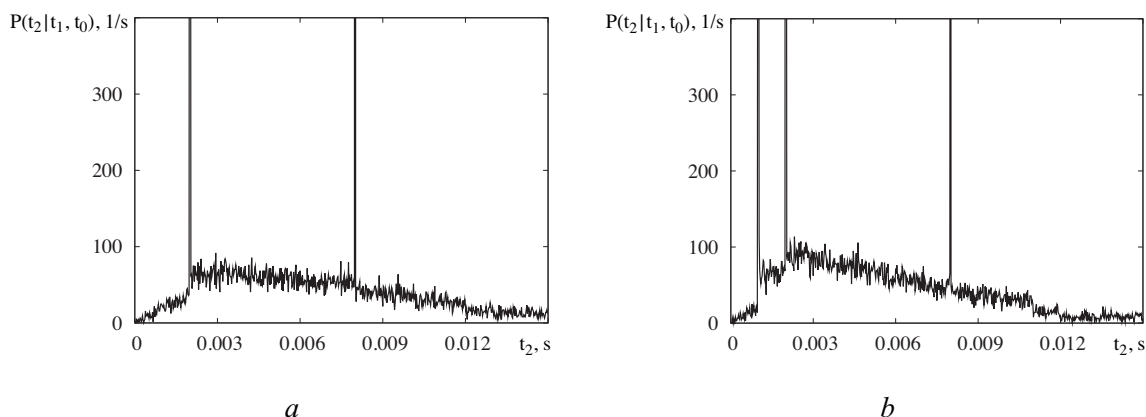


Fig. 6. Conditional probability density $P(t_2 | t_1, t_0)$ for $\tau = 10$ ms, $\Delta = 8$ ms, $\lambda = 150$ s⁻¹, $N_0 = 2$, $t_1 = 6$ ms, $t_0 = 3$ ms (a) and $t_1 = 6$ ms, $t_0 = 1$ ms (b), found numerically by means of Monte-Carlo method ($N = 30\,000$). Different course of $P(t_2 | t_1, t_0)$ for different t_0 values is clearly visible.

$$P^{\text{sing}}(t_2 | t_1, t_0) =$$

$$= \begin{cases} e^{-\lambda t_2} \lambda t_2 \delta(t_2 - \Delta), & (t_0, t_1) \in D_2 \cup D_3 \cup d, & (52) \\ e^{-\lambda t_2} \lambda t_2 \delta(t_1 + t_2 - \Delta), & (t_0, t_1) \in D_4, & (53) \\ \frac{e^{-\lambda t_2} \lambda t_2}{P(t_1, t_0)} \left(F(t_1 | \Delta) \int_0^{t_0} F(t_0 | s_0) f(s_0) ds_0 \delta(t_1 + t_2 - \Delta) + \right. \\ \left. + \int_{t_0}^{\Delta} F(t_1 | s_0 - t_0) F(t_0 | s_0) f(s_0) ds_0 \delta(t_2 - \Delta) \right), & (t_0, t_1) \in D_5, & (54) \\ \frac{e^{-\lambda t_2} \lambda t_2}{P(t_1, t_0)} \left(\int_{t_0}^{t_0+t_1} F(t_1 | s_0 - t_0) F(t_0 | s_0) f(s_0) ds_0 \delta(t_2 - \Delta) + \right. \\ \left. + F(t_1 | \Delta) \int_0^{t_0} F(t_0 | s_0) f(s_0) ds_0 \delta(t_1 + t_2 - \Delta) + \right. \\ \left. + a F(t_1 | \Delta - t_0) F(t_0 | \Delta) \delta(t_0 + t_1 + t_2 - \Delta) \right), & (t_0, t_1) \in D_1. & (55) \end{cases}$$

Obviously, expression (55) could be obtained directly from (34)–(36) by substituting $n = 1$.

As one can see, the singular part of $P(t_2 | t_1, t_0)$ depends on t_0 , therefore $P(t_2 | t_1, t_0)$ cannot be reduced to $P(t_2 | t_1)$, which means that the output stream is not first-order Markovian.

Examples of $P(t_2 | t_1, t_0)$, found numerically for different domains, are placed at Figs 5 and 6.

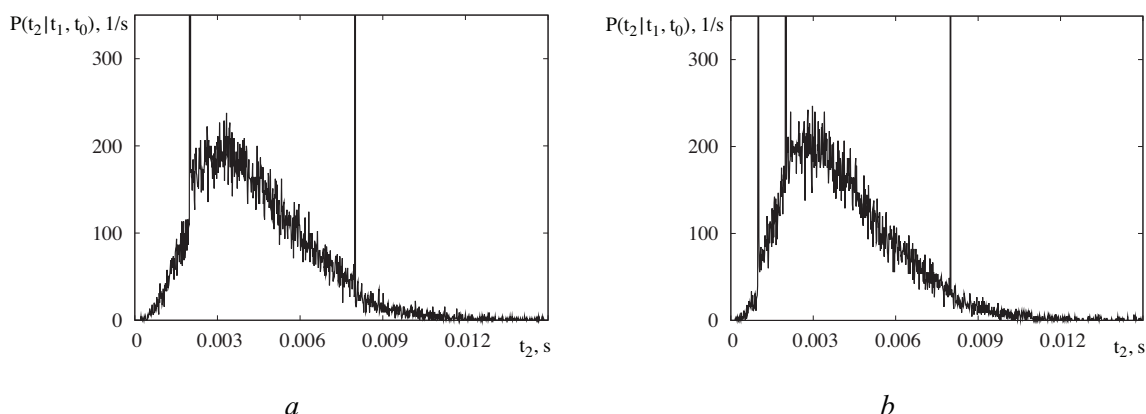


Fig. 7. Conditional probability density $P(t_2 | t_1, t_0)$ for $\tau = 10$ ms, $\Delta = 8$ ms, $\lambda = 800$ s $^{-1}$, $N_0 = 4$, $t_1 = 6$ ms, $t_0 = 3$ ms (a) and $t_1 = 6$ ms, $t_0 = 1$ ms (b), found numerically by means of Monte-Carlo method ($N = 30\,000$). Different course of $P(t_2 | t_1, t_0)$ for different t_0 values is clearly visible.

7. Numerical simulation. In order to check the correctness of obtained analytic expressions, and also to investigate whether the output ISIs stream is non-Markovian for BN with higher thresholds as well as for $N_0 = 2$, numerical simulations were performed. A C++ program, containing class, which models the operation manner of BN with delayed feedback, was developed. Object of this class receives the sequence of pseudorandom numbers with Poisson probability density to its input. The required sequences were generated by means of utilities from the GNU Scientific Library³ with the Mersenne Twister generator as source of pseudorandom numbers.

Program contains function, the time engine, which brings system to the moment just before the next input signal, bypassing moments, when neither external Poisson impulse, nor impulse from the feedback line comes. So, only the essential discrete events are accounted. It allows one to make exact calculations faster as compared to the algorithm where time advances gradually by adding small time-steps.

The conditional probability densities, $P(t_1 | t_0)$ and $P(t_2 | t_1, t_0)$, are found by counting the number of output ISI of different durations and normalization (see Figs 4–7). For calculation of conditional distributions only those ISIs are selected, which follow one or two ISIs of fixed duration, namely, $\{t_0\}$ for $P(t_1 | t_0)$ and $\{t_1, t_0\}$ for $P(t_2 | t_1, t_0)$. The quantity, the position and the mass of δ -functions, obtained in numerical experiments for BN with threshold 2, coincide with those predicted analytically in (43), (44) and (52) – (55).

For $N_0 > 2$, conditional probability densities $P(t_1 | t_0)$ and $P(t_2 | t_1, t_0)$ are similar to those, found for $N_0 = 2$. In particular, both the quantity and position of δ -functions coincide with those obtained for BN with threshold 2, as expected, compare Figs 6 and 7.

8. Conclusions and discussion. Our results reveal the influence of delayed feedback presence on the neuronal firing statistics. In contrast to the cases of BN without feedback [38] and BN with instantaneous feedback [39], the neighbouring output ISIs of BN with delayed feedback are mutually

³<http://www.gnu.org/software/gsl/>

correlated. It means that even in the simplest possible recurrent network the output ISI stream cannot be treated as a renewal one.

The non-renewalness of experimentally registered spike trains was observed for neuronal activity in various sensory systems in mammals [9] and fish [10, 11]. The simplest stochastic processes which are not renewal are the Markov processes of various order. The order of underlying Markov process was estimated in [11] for activity in the weakly electric fish electrosensory system. It was found in [11] that for some neural fibers the Markov order should be at list seven, which does not exclude that the genuine order is higher, or that the activity is non-Markovian.

Actually, for proving based on experimental data that a stochastic activity has Markov order m , one needs increasing amount of data with increasing m . If so, it seems impossible to prove experimentally that a stochastic activity is non-Markovian. Similarly as it is impossible to prove experimentally that a number is irrational. We prove here that the output ISI stream of BN with delayed feedback is non-Markovian based on complete knowledge of the mechanism which generates the output stream. In a sense, to have this knowledge is equivalent as to have unlimited amount of experimental data.

The main cause of non-Markovianness in our case is the delayed feedback presence. In this connection, it would be interesting to compare our results with recently appeared paper [42], where the discrete time recurrent model network of leaky integrate-and-fire (LIF) neurons is considered. In that model, the inter-neuronal communication lines have zero delays and external input is deterministic, but synaptic weights are subjected to uncorrelated random fluctuations. For that model, it is established that the stochastic process of neuronal firing states will be non-Markovian as well. What could be the reason of non-Markovianness if there are no delays in this model? The answer is that LIF neuron has infinite memory unless its state is reset by firing. The instantaneous firing state of the network specifies which neurons are in the firing state at the given moment of discrete time, but says nothing about the excitation level of neurons, which are quiescent at that moment. This unknown level of excitation is due to firing of neighbouring neurons at earlier moments of time. Therefore, knowledge of the firing states at more and more early moments can more and more improve our predicting ability as regards states of the quiescent neurons at the given moment, and finally, as regards the network firing state at the next moment. Any neighbouring neuron could have its last firing moment infinitely far in the past and this explains why a network without communication delays can as well demonstrate non-Markovian behavior.

Given that in the considered system of single neuron with delayed feedback the non-Markovian character arises exclusively from delayed communication, it is natural to consider that this property (non-Markovianness) will be present in any single neuron, whenever delayed feedback constitutes an important input, independently on the specific neuronal model at hand. In a network composed of more than single neuron with feedback, the delayed feedback can be mediated with inter-neurons, and our finding suggests that behavior of such a network will be non-Markovian as well. One should take this facts into account during analysis of neuronal spike trains obtained from any recurrent network with delayed inter-neuronal communication.

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